

偏心圆柱薄壳的分析*

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摘 要

本文推导了偏心圆柱薄壳小挠度时的近似方程, 并利用解析方法求解了该方程, 得出了偏心圆柱薄壳的应力、位移与偏心距之间的关系。

关键词 偏心圆柱薄壳 小挠度 近似方程

一、引 言

薄壳、薄板在许多行业中有着广泛的应用, 而圆柱薄壳由于形状特殊、性能稳定, 便于分析计算又倍受重视。对于同心圆柱薄壳, 其线性理论已趋于成熟。但在实际应用中往往见到偏心圆柱薄壳, 而偏心圆柱薄壳的理论分析迄今尚未见到。本文详细地分析了偏心圆柱薄壳, 推导出了它的近似方程, 并采用解析方法得出了它的解析解, 从而给出了它的应力、位移与偏心距的关系。

二、基本方程及解

偏心圆柱薄壳横截面如图1所示, A 为外圆圆心, r_1 为外圆半径, B 为内圆圆心, r_2 为内圆半径, O 为 AB 中点, e 为偏心距, 柱高

L , 上、下边界固定, 受均布内压 p 。

在我们所考虑的范围

$$e < 0.1(r_1 - r_2) \sim 0.2(r_1 - r_2) \quad (2.1)$$

$$r_1 - r_2 \ll r_1, r_2 \quad (2.2)$$

外圆方程

$$r_w^2 + \frac{e^2}{4} + er_w \cos\theta = r_1^2 \quad (2.3)$$

内圆方程

$$r_s^2 + \frac{e^2}{4} - er_s \cos\theta = r_2^2 \quad (2.4)$$

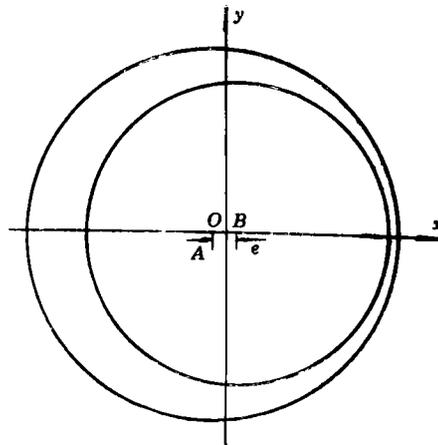


图 1

* 樊大钧推荐。

(2.3) - (2.4)

$$\begin{aligned} r_w^2 - r_n^2 + e \cos \theta (r_w + r_n) &= r_1^2 - r_2^2 \\ (r_w + r_n)(r_w - r_n) + e \cos \theta (r_w + r_n) &= (r_1 + r_2)(r_1 - r_2) \end{aligned} \quad (2.5)$$

$$\text{记 } h = r_w - r_n, \quad h_c = r_1 - r_2 \quad (2.6)$$

则 h 为偏心圆柱薄壳的厚度, h_c 为无偏心时的厚度.

注意到 (2.1)、(2.2), 可得

$$r_w + r_n = r_1 + r_2 \quad (2.7)$$

将 (2.6)、(2.7) 代入 (2.5) 化简可得

$$h = h_0 + h_1 e \quad (2.8)$$

式中 $h_0 = h_c$

$$h_1 = -\cos \theta$$

经过以上分析, 偏心圆柱薄壳可视为中面半径 $R = \frac{r_1 + r_2}{2}$, 厚度 $h = h_0 + h_1 e$ 的变厚度圆柱薄壳.

如图 2 所示, 以 c 点为原点, 以母线为 α 线, 以圆周线为 β 线, 以法线为 γ 线建立正交曲线坐标系. 图 2 所示面为垂直方向的对称面.

根据壳体理论可得如下方程组.

平衡方程

$$\frac{\partial N_1}{\partial \alpha} + \frac{\partial N_{12}}{\partial \beta} = 0 \quad (2.9)$$

$$\frac{\partial N_2}{\partial \beta} + \frac{\partial N_{12}}{\partial \alpha} = 0 \quad (2.10)$$

$$-\frac{N_2}{R} + 2 \frac{\partial^2 M_{12}}{\partial \alpha \partial \beta} + \frac{\partial^2 M_1}{\partial \alpha^2} + \frac{\partial^2 M_2}{\partial \beta^2} + p = 0 \quad (2.11)$$

物理方程

$$N_1 = \frac{Eh}{1-\mu^2} \left[\frac{\partial u}{\partial \alpha} + \mu \left(\frac{\partial v}{\partial \beta} + \frac{w}{R} \right) \right] \quad (2.12)$$

$$N_2 = \frac{Eh}{1-\mu^2} \left[\left(\frac{\partial v}{\partial \beta} + \frac{w}{R} \right) + \mu \frac{\partial u}{\partial \alpha} \right] \quad (2.13)$$

$$N_{12} = \frac{Eh}{2(1+\mu)} \left(\frac{\partial u}{\partial \beta} + \frac{\partial v}{\partial \alpha} \right) \quad (2.14)$$

$$M_1 = -D \left[\frac{\partial^2 w}{\partial \alpha^2} + \mu \frac{\partial^2 w}{\partial \beta^2} \right] \quad (2.15)$$

$$M_2 = -D \left[\frac{\partial^2 w}{\partial \beta^2} + \mu \frac{\partial^2 w}{\partial \alpha^2} \right] \quad (2.16)$$

$$M_{12} = -D(1-\mu) \frac{\partial^2 w}{\partial \alpha \partial \beta} \quad (2.17)$$

式中 E 为弹性模量, μ 为泊松比

$$D = \frac{Eh^3}{12(1-\mu^2)}$$

因为 $h - h_0 = -e \cos \theta$ 是个小量, 可设



图 2

$$(h-h_0)^2=0 \quad (2.18)$$

$$(h-h_0)^3=0 \quad (2.19)$$

由(2.18)得

$$h^2 = -h_0^2 + 2h_0h \quad (2.20)$$

由(2.19)得

$$h^3 = -3h_0^2h + 3h_0h^2 + h_0^3 \quad (2.21)$$

将(2.8)、(2.20)代入(2.21)整理得

$$h^3 = h_0^3 + 3h_0^2h_1e, \quad D = D_0 + D_1e \quad (2.22)$$

式中

$$D_0 = \frac{Eh_0^3}{12(1-\mu^2)}$$

$$D_1 = \frac{3Eh_0^2h_1}{12(1-\mu^2)}$$

设 $N_1 = N_{10} + N_{11}e, \quad N_2 = N_{20} + N_{21}e$

$$N_{12} = N_{120} + N_{121}e$$

$$M_1 = M_{10} + M_{11}e, \quad M_2 = M_{20} + M_{21}e$$

$$M_{12} = M_{120} + M_{121}e$$

$$u = u_0 + u_1e, \quad v = v_0 + v_1e$$

$$w = w_0 + w_1e$$

将(2.8)、(2.22)以及以上诸式代入(2.9)~(2.17), 比较 e 的零次项、一次项得

$$\frac{\partial N_{10}}{\partial \alpha} + \frac{\partial N_{120}}{\partial \beta} = 0 \quad (2.23)$$

$$\frac{\partial N_{20}}{\partial \beta} + \frac{\partial N_{120}}{\partial \alpha} = 0 \quad (2.24)$$

$$-\frac{N_{20}}{R} + 2\frac{\partial^2 \mu_{120}}{\partial \alpha \partial \beta} + \frac{\partial^2 M_{10}}{\partial \alpha^2} + \frac{\partial^2 M_{20}}{\partial \beta^2} + p = 0 \quad (2.25)$$

$$N_{10} = \frac{Eh_0}{1-\mu^2} \left[\frac{\partial u_0}{\partial \alpha} + \mu \left(\frac{\partial v_0}{\partial \beta} + \frac{w_0}{R} \right) \right] \quad (2.26)$$

$$N_{20} = \frac{Eh_0}{1-\mu^2} \left[\left(\frac{\partial v_0}{\partial \beta} + \frac{w_0}{R} \right) + \mu \frac{\partial u_0}{\partial \alpha} \right] \quad (2.27)$$

$$N_{120} = \frac{Eh_0}{2(1+\mu)} \left(\frac{\partial u_0}{\partial \beta} + \frac{\partial v_0}{\partial \alpha} \right) \quad (2.28)$$

$$M_{10} = -D_0 \left(\frac{\partial^2 w_0}{\partial \alpha^2} + \mu \frac{\partial^2 w_0}{\partial \beta^2} \right) \quad (2.29)$$

$$M_{20} = -D_0 \left(\frac{\partial^2 w_0}{\partial \beta^2} + \mu \frac{\partial^2 w_0}{\partial \alpha^2} \right) \quad (2.30)$$

$$M_{120} = -D_0(1-\mu) \frac{\partial^2 w_0}{\partial \alpha \partial \beta} \quad (2.31)$$

$$\frac{\partial N_{11}}{\partial \alpha} + \frac{\partial N_{121}}{\partial \beta} = 0 \quad (2.32)$$

$$\frac{\partial N_{21}}{\partial \beta} + \frac{\partial N_{121}}{\partial \alpha} = 0 \quad (2.33)$$

$$-\frac{N_{21}}{R} + 2 \frac{\partial^2 M_{121}}{\partial \alpha \partial \beta} + \frac{\partial^2 M_{11}}{\partial \alpha^2} + \frac{\partial^2 M_{21}}{\partial \beta^2} = 0 \quad (2.34)$$

$$N_{11} = \frac{Eh_0}{1-\mu^2} \left[\frac{\partial u_1}{\partial \alpha} + \mu \left(\frac{\partial v_1}{\partial \beta} + \frac{w_1}{R} \right) \right] \\ + \frac{Eh_1}{1-\mu^2} \left[\frac{\partial u_0}{\partial \alpha} + \mu \left(\frac{\partial v_0}{\partial \beta} + \frac{w_0}{R} \right) \right] \quad (2.35)$$

$$N_{21} = \frac{Eh_0}{1-\mu^2} \left[\left(\frac{\partial v_1}{\partial \beta} + \frac{w_1}{R} \right) + \mu \frac{\partial u_1}{\partial \alpha} \right] \\ + \frac{Eh_1}{1-\mu^2} \left[\left(\frac{\partial v_0}{\partial \beta} + \frac{w_0}{R} \right) + \mu \frac{\partial u_0}{\partial \alpha} \right] \quad (2.36)$$

$$N_{121} = \frac{Eh_0}{2(1+\mu)} \left(\frac{\partial u_1}{\partial \beta} + \frac{\partial v_1}{\partial \alpha} \right) \\ + \frac{Eh_1}{2(1+\mu)} \left(\frac{\partial u_0}{\partial \beta} + \frac{\partial v_0}{\partial \alpha} \right) \quad (2.37)$$

$$M_{11} = -D_0 \left(\frac{\partial^2 w_1}{\partial \alpha^2} + \mu \frac{\partial^2 w_1}{\partial \beta^2} \right) \\ - D_1 \left(\frac{\partial^2 w_0}{\partial \alpha^2} + \mu \frac{\partial^2 w_0}{\partial \beta^2} \right) \quad (2.38)$$

$$M_{21} = -D_0 \left(\frac{\partial^2 w_1}{\partial \beta^2} + \mu \frac{\partial^2 w_1}{\partial \alpha^2} \right) \\ - D_1 \left(\frac{\partial^2 w_0}{\partial \beta^2} + \mu \frac{\partial^2 w_0}{\partial \alpha^2} \right) \quad (2.39)$$

$$M_{121} = -D_0(1-\mu) \frac{\partial^2 w_1}{\partial \alpha \partial \beta} - D_1(1-\mu) \frac{\partial^2 w_0}{\partial \alpha \partial \beta} \quad (2.40)$$

边界条件

$$\alpha = \pm L \text{ 处 } \quad w_0 = 0, \quad \frac{dw_0}{d\alpha} = 0 \quad (2.41)$$

$$v_0 = 0 \quad (2.42)$$

$$\frac{du_0}{d\alpha} = 0 \quad (2.43)$$

$$w_1 = 0, \quad \frac{dw_1}{d\alpha} = 0 \quad (2.44)$$

$$v_1 = 0 \quad (2.45)$$

$$\frac{du_1}{d\alpha} = 0 \quad (2.46)$$

方程(2.23)~(2.31)在边界条件(2.41)~(2.43)下等价于两端固定的无偏心圆柱薄壳，
易得

$$u_0 = -\frac{\mu}{R} [c_1 \sin \lambda \alpha \operatorname{ch} \lambda \alpha + c_2 \cos \lambda \alpha \operatorname{sh} \lambda \alpha] \quad (2.47)$$

$$v_0 = 0 \tag{2.48}$$

$$w_0 = c_3 \sin \lambda a \operatorname{sh} \lambda a + c_4 \cos \lambda a \operatorname{ch} \lambda a + \frac{pR^2}{Eh} \tag{2.49}$$

式中

$$\lambda = \left[\frac{Eh_0}{4R^2D} \right]^{1/4}$$

$$c_1 = - \frac{4 \sin \lambda L \operatorname{ch} \lambda L}{\sin 2\lambda L + \operatorname{sh} 2\lambda L} \frac{pR^2}{Eh_0 \lambda}$$

$$c_2 = - \frac{4 \cos \lambda L \operatorname{sh} \lambda L}{\sin 2\lambda L + \operatorname{sh} 2\lambda L} \frac{pR^2}{Eh_0 \lambda}$$

$$c_3 = - \frac{2(\sin \lambda L \operatorname{ch} \lambda L - \cos \lambda L \operatorname{sh} \lambda L)}{\sin 2\lambda L + \operatorname{sh} 2\lambda L} \frac{pR^2}{Eh_0}$$

$$c_4 = - \frac{2(\sin \lambda L \operatorname{ch} \lambda L + \cos \lambda L \operatorname{sh} \lambda L)}{\sin 2\lambda L + \operatorname{sh} 2\lambda L} \frac{pR^2}{Eh_0}$$

将(2.35)~(2.40)、(2.47)~(2.49)代入(2.32)~(2.34)，忽略 h/R 级小量，整理得

$$\begin{aligned} & \left(\frac{\partial^2}{\partial \alpha^2} + \frac{1-\mu}{2} \frac{\partial^2}{\partial \beta^2} \right) u_1 + \frac{1+\mu}{2} \frac{\partial^2 v_1}{\partial \alpha \partial \beta} + \frac{\mu}{R} \frac{\partial w_1}{\partial \alpha} \\ & = (d_1 \sin \lambda a \operatorname{ch} \lambda a + d_2 \cos \lambda a \operatorname{sh} \lambda a) \cos \theta \end{aligned} \tag{2.50}$$

$$\begin{aligned} & \frac{1+\mu}{2} \frac{\partial^2 u_1}{\partial \alpha \partial \beta} + \left(\frac{\partial^2}{\alpha \beta^2} + \frac{1-\mu}{2} \frac{\partial^2}{\partial \alpha^2} \right) v_1 + \frac{1}{R} \frac{\partial w_1}{\partial \beta} \\ & = (d_3 \sin \lambda a \operatorname{sh} \lambda a + d_4 \cos \lambda a \operatorname{ch} \lambda a) \sin \theta \end{aligned} \tag{2.51}$$

$$\begin{aligned} & \frac{\mu}{R} \frac{\partial u_1}{\partial \alpha} + \frac{1}{R} \frac{\partial v_1}{\partial \beta} + \frac{w_1}{R^2} + \frac{h_0^2}{12} \nabla^2 \nabla^2 w_1 \\ & = (d_5 \sin \lambda a \operatorname{sh} \lambda a + d_6 \cos \lambda a \operatorname{ch} \lambda a + d_7) \cos \theta \end{aligned} \tag{2.52}$$

式中

$$d_1 = \frac{\mu}{Rh_0} [2\lambda^2 c_2 + \lambda(c_3 - c_4)]$$

$$d_2 = \frac{\mu}{Rh_0} [-2\lambda^2 c_1 + \lambda(c_3 + c_4)]$$

$$d_3 = \frac{1}{Rh_0} \left[\frac{c_4}{R} - \frac{\mu^2}{R} \lambda (c_1 + c_2) \right]$$

$$d_4 = \frac{1}{Rh_0} \left[\frac{c_3}{R} - \frac{\mu^2}{R} \lambda (c_1 - c_2) \right]$$

$$d_5 = \left(-\frac{1}{R^2 h_0} + \frac{3(1-\mu^2)}{R^2 h_0} \right) c_3 + \frac{\mu^2}{R^2 h_0} \lambda (c_1 - c_2)$$

$$d_6 = \left(-\frac{1}{R^2 h_0} + \frac{3(1-\mu^2)}{R^2 h_0} \right) c_4 + \frac{\mu^2}{R^2 h_0} \lambda (c_1 + c_2)$$

$$d_7 = -\frac{p}{Eh_0^2}$$

因为 u_1 、 w_1 是 θ 的偶函数， v_1 是 θ 的奇函数，并注意到(2.50)~(2.52)的特点，可设

$$u_1 = u_{10} + u_{12} \cos \theta \tag{2.53}$$

$$v_1 = v_{11} \sin \theta \tag{2.54}$$

$$w_1 = w_{10} + w_{12} \cos \theta \tag{2.55}$$

将(2.53)~(2.55)代入(2.50)~(2.52)，整理并比较 $\sin \theta$ 、 $\cos \theta$ 的系数及不含 θ 的项可得：

$$u''_{10} + \frac{\mu}{R} w'_{10} = 0 \quad (2.56)$$

$$\frac{\mu}{R} u'_{10} + \frac{1}{R^2} w_{10} + \frac{h_0^2}{12} w''''_{10} = 0 \quad (2.57)$$

$$u''_{12} - \frac{1-\mu}{2R^2} u_{12} + \frac{1+\mu}{2R} v'_{11} + \frac{\mu}{R} w'_{12} \\ = d_1 \sin \lambda a \operatorname{ch} \lambda a + d_2 \cos \lambda a \operatorname{sh} \lambda a \quad (2.58)$$

$$-\frac{1+\mu}{2R} u'_{12} - \frac{1}{R^2} v_{11} + \frac{1-\mu}{2} v''_{11} - \frac{1}{R^2} w_{12} \\ = d_3 \sin \lambda a \operatorname{ch} \lambda a + d_4 \cos \lambda a \operatorname{sh} \lambda a \quad (2.59)$$

$$\frac{\mu}{R} u'_{12} + \frac{1}{R^2} v_{11} + \frac{1}{R^2} w_{12} + \frac{h_0^2}{12} w''''_{12} \\ = d_5 \sin \lambda a \operatorname{sh} \lambda a + d_6 \cos \lambda a \operatorname{ch} \lambda a + d_7 \quad (2.60)$$

式中 $()' = \frac{d}{d\alpha} ()$

边界条件化为

$$\alpha = \pm L \text{ 处 } w_{10} = 0, \quad \frac{dw_{10}}{d\alpha} = 0 \quad (2.61)$$

$$\frac{du_{10}}{d\alpha} = 0 \quad (2.62)$$

$$w_{12} = 0, \quad \frac{dw_{12}}{d\alpha} = 0 \quad (2.63)$$

$$v_{11} = 0 \quad (2.64)$$

$$\frac{du_{12}}{d\alpha} = 0 \quad (2.65)$$

在条件(2.61)、(2.62)下求解(2.56)、(2.57)得

$$u_{10} = 0, \quad w_{10} = 0 \quad (2.66)$$

联立(2.58)~(2.60), 消去 u_{12} , 忽略 h/R 级小量, 可得

$$w''''_{12} + \frac{1-\mu}{1+\mu} \frac{12}{R^2 h_0^2} (w_{12} + v_{11}) + \frac{12}{h_0^2} \frac{\mu(1-\mu)}{1+\mu} v''_{11} \\ = e_1 \sin \lambda a \operatorname{sh} \lambda a + e_2 \cos \lambda a \operatorname{ch} \lambda a + e_3 \quad (2.67)$$

$$v''''_{11} = e_4 \sin \lambda a \operatorname{sh} \lambda a + e_5 \cos \lambda a \operatorname{ch} \lambda a \quad (2.68)$$

式中

$$e_1 = -\frac{12}{h_0^2} \left(d_5 + \frac{2\mu}{1+\mu} d_3 \right)$$

$$e_2 = \frac{12}{h_0^2} \left(d_6 + \frac{2\mu}{1+\mu} d_4 \right)$$

$$e_3 = -\frac{12}{h_0^2} d_7$$

$$e_4 = \frac{1+\mu}{1-\mu} \frac{1}{R} (d_1 - d_2) \lambda - \frac{4}{1-\mu} d_4 \lambda^2 + \frac{1}{R^2} d_3$$

$$e_5 = \frac{1+\mu}{1-\mu} \frac{1}{R} (d_1 + d_2) \lambda + \frac{4}{1-\mu} d_3 \lambda^3 + \frac{1}{R^2} d_4$$

由(2.59)、(2.63)~(2.65)得

$$\alpha = \pm L \text{ 处, } v''_{11} = \frac{2}{1-\mu} [d_3 \sin \lambda L \operatorname{sh} \lambda L + d_4 \cos \lambda L \operatorname{ch} \lambda L] \quad (2.69)$$

由(2.64)、(2.68)、(2.69)得

$$v_{11} = c\alpha^2 + d - \frac{e_4}{4\lambda^4} \sin \lambda \alpha \operatorname{sh} \lambda \alpha - \frac{e_5}{4\lambda^4} \cos \lambda \alpha \operatorname{ch} \lambda \alpha \quad (2.70)$$

式中

$$c = -\frac{e_5}{4\lambda^2} \sin \lambda L \operatorname{sh} \lambda L + \frac{e_4}{4\lambda^2} \cos \lambda L \operatorname{ch} \lambda L$$

$$d = \frac{e_4}{4\lambda^4} \sin \lambda L \operatorname{sh} \lambda L + \frac{e_5}{4\lambda^4} \cos \lambda L \operatorname{ch} \lambda L - cL^2$$

将(2.70)代入(2.67),并在条件(2.63)下求解得

$$\begin{aligned} w_{12} = & f_1 \sin \lambda_1 \alpha \operatorname{sh} \lambda_1 \alpha + f_2 \cos \lambda_1 \alpha \operatorname{ch} \lambda_1 \alpha \\ & + f_3 \sin \lambda \alpha \operatorname{sh} \lambda \alpha + f_4 \cos \lambda \alpha \operatorname{ch} \lambda \alpha \\ & + f_5 \alpha^2 + f_6 \end{aligned} \quad (2.71)$$

式中

$$\lambda_1 = \left[\frac{1-\mu}{1+\mu} \frac{3}{R^2 h_0^2} \right]^{1/4}$$

$$f_3 = \frac{1}{4(\lambda_1^4 - \lambda^4)} \left[e_1 + \frac{1-\mu}{1+\mu} \frac{3}{R^2 h_0^2 \lambda^4} e_4 - \frac{6}{h_0^2} \frac{\mu(1-\mu)}{1+\mu} \frac{1}{\lambda^2} e_5 \right]$$

$$f_4 = \frac{1}{4(\lambda_1^4 - \lambda^4)} \left[e_2 - \frac{1-\mu}{1+\mu} \frac{3}{R^2 h_0^2 \lambda^4} e_5 + \frac{6}{h_0^2} \frac{\mu(1-\mu)}{1+\mu} \frac{1}{\lambda^2} e_4 \right]$$

$$f_5 = -c$$

$$f_6 = \frac{1+\mu}{1-\mu} \frac{R^2 h_0^2}{12} e_3 - 2\mu R^2 c - d$$

$$f_1 = \frac{\Delta_1}{\Delta}, \quad f_2 = \frac{\Delta_2}{\Delta}$$

$$\Delta = -\lambda(\sin_2 \lambda_1 L + \operatorname{sh}_2 \lambda_1 L)$$

$$\Delta_1 = \lambda[-\sin \lambda_1 L \operatorname{ch} \lambda_1 L + \cos \lambda_1 L \operatorname{sh} \lambda_1 L] g_1 - \cos \lambda_1 L \operatorname{ch} \lambda_1 L g_2$$

$$\Delta_2 = -\lambda[\cos \lambda_1 L \operatorname{sh} \lambda_1 L + \sin \lambda_1 L \operatorname{ch} \lambda_1 L] g_1 + \sin \lambda_1 L \operatorname{sh} \lambda_1 L g_2$$

$$g_1 = -f_3 \sin \lambda L \operatorname{sh} \lambda L - f_4 \cos \lambda L \operatorname{ch} \lambda L - f_5 L^2 - f_6$$

$$\begin{aligned} g_2 = & -f_3 [\lambda \cos \lambda L \operatorname{sh} \lambda L + \lambda \sin \lambda L \operatorname{ch} \lambda L] \\ & - f_4 [-\lambda \sin \lambda L \operatorname{ch} \lambda L + \lambda \cos \lambda L \operatorname{sh} \lambda L] \\ & - 2f_5 L \end{aligned}$$

将(2.70)、(2.71)代入(2.60)整理得

$$\begin{aligned} u'_{12} = & s_1 \sin \lambda_1 \alpha \operatorname{sh} \lambda_1 \alpha + s_2 \cos \lambda_1 \alpha \operatorname{ch} \lambda_1 \alpha + s_3 \sin \lambda \alpha \operatorname{sh} \lambda \alpha \\ & + s_4 \cos \lambda \alpha \operatorname{ch} \lambda \alpha + s_5 \end{aligned} \quad (2.72)$$

式中

$$s_1 = \frac{R h_0^2 f_1}{48 \mu \lambda_1^4}$$

$$s_2 = \frac{R h_0^2 f_2}{48 \mu \lambda_1^4}$$

$$s_3 = -\frac{1}{\mu R} \left(f_3 - \frac{e_4}{4\lambda^4} \right) + \frac{R h_0^2 f_3}{48 \mu \lambda^4} + \frac{R}{\mu} d_5$$

$$s_4 = -\frac{1}{\mu R} \left(f_4 - \frac{e_5}{4\lambda^4} \right) + \frac{R h_0^2 f_4}{48\mu\lambda^4} + \frac{R}{\mu} d_6$$

$$s_5 = -\frac{1}{\mu R} \left[\frac{1+\mu}{1-\mu} \frac{R^2 h_0^2}{12} e_3 - 2\mu R^2 c \right] + \frac{R}{\mu} d_7$$

由(2.72)、并注意到 $\alpha=0$ 处 $u_{1,2}=0$ 可得

$$u_{1,2} = t_1 \sin \lambda_1 \alpha \operatorname{ch} \lambda_1 \alpha + t_2 \cos \lambda_1 \alpha \operatorname{sh} \lambda_1 \alpha + t_3 \sin \lambda \alpha \operatorname{ch} \lambda \alpha + t_4 \cos \lambda \alpha \operatorname{sh} \lambda \alpha + s_5 \alpha \quad (2.73)$$

式中

$$t_1 = \frac{s_1 + s_2}{2} \frac{1}{\lambda_1}$$

$$t_2 = \frac{s_2 - s_1}{2} \frac{1}{\lambda_1}$$

$$t_3 = \frac{s_3 + s_4}{2} \frac{1}{\lambda}$$

$$t_4 = \frac{s_4 - s_3}{2} \frac{1}{\lambda}$$

至此,我们得出了位移

$$u = -\frac{\mu}{R} [c_1 \sin \lambda \alpha \operatorname{ch} \lambda \alpha + c_2 \cos \lambda \alpha \operatorname{sh} \lambda \alpha] + [t_1 \sin \lambda_1 \alpha \operatorname{ch} \lambda_1 \alpha + t_2 \cos \lambda_1 \alpha \operatorname{sh} \lambda_1 \alpha + t_3 \sin \lambda \alpha \operatorname{ch} \lambda \alpha + t_4 \cos \lambda \alpha \operatorname{sh} \lambda \alpha + s_5 \alpha] \cos \theta \cdot e \quad (2.74)$$

$$v = \left[c\alpha^2 + d - \frac{e_4}{4\lambda^4} \sin \lambda \alpha \operatorname{sh} \alpha - \frac{e_5}{4\lambda^4} \cos \lambda \alpha \operatorname{ch} \lambda \alpha \right] \sin \theta \cdot e \quad (2.75)$$

$$w = c_3 \sin \lambda \alpha \operatorname{sh} \lambda \alpha + c_4 \cos \lambda \alpha \operatorname{ch} \lambda \alpha + \frac{pR^2}{Eh_0} + [f_1 \sin \lambda_1 \alpha \operatorname{sh} \lambda_1 \alpha + f_2 \cos \lambda_1 \alpha \operatorname{ch} \lambda_1 \alpha + f_3 \sin \lambda \alpha \operatorname{sh} \lambda \alpha + f_4 \cos \lambda \alpha \operatorname{ch} \lambda \alpha + f_5 \alpha^2 + f_6] \cos \theta \cdot e \quad (2.76)$$

将(2.74)~(2.76)代入(2.12)~(2.17)即可得到内力和弯矩,限于篇幅,这里不再列出。

Analysis of the Eccentric Cylindrical Thin Shell

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Abstract

This paper gives the approximate equations of the eccentric cylindrical thin shell under small deflections. By means of the analytical method, we solved the equations. Thus the relations between the stress, the displacement and the eccentricity of the eccentric cylindrical thin shell are obtained.

Key words eccentric cylindrical thin shell, small deflections, approximate equations