

关于非线性初边值问题的奇摄动(Ⅱ)*

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摘 要

本文研究一类似线性双曲—抛物型方程, 具有变动边界的初边值问题的奇摄动:

$$\varepsilon \frac{\partial^2 u_i}{\partial t^2} + \frac{\partial u_i}{\partial t} = A\left(x, t, u_i, \frac{\partial u_i}{\partial x}\right) \frac{\partial^2 u_i}{\partial x^2} + F\left(x, t, u_i, \frac{\partial u_i}{\partial x}\right)$$
$$u_i(x, 0) = \varphi_0(x), \quad \frac{\partial u_i}{\partial t}(x, 0) = \varphi_1(x); \quad \frac{\partial u_i}{\partial x}(l_i(t), t) = \psi_i(t), \quad (i=0, 1)$$

在某些条件成立, 且 ε 充分小时, 此问题的解具有以退化问题充分光滑解为首项的广义渐近展开式(Van der Corput意义), 它在充分光滑解存在的区域 $Q = \{(x, t) | l_0(t) \leq x \leq l_1(t), 0 \leq t \leq T\}$ 上一致有效. 其边界层存在于 $t=0$ 附近. 本文是工作[3]~[5]的进一步发展.

关键词 奇摄动 变动边界 渐近展开式

一、引 言

在部分高阶导数带有小参数的偏微分方程奇摄动问题的研究中, 椭圆—抛物型方程研究得较多, 而双曲—抛物型方程的研究则比较少. 自1959年起有这样一些成果: M. Zlamal和江福汝分别研究了线性双曲—抛物型方程混合问题^{[1],[2]}. 至1983年, 高汝熹研究了拟线性双曲—抛物型方程的混合问题^[3]. 作者则对具有非线性初边值条件的拟线性双曲—抛物型方程的奇摄动进行过研究^{[4],[5]}. 在本文中, 我们将对初边值问题的更一般情况, 即具有变动边界的情况进行讨论.

当某些假定条件满足而 ε 充分小时, 这样的问题的解具有一个广义渐近展开式(Van der Corput意义). 通过能量不等式的建立, 得到渐近展开式在一个有界区域上一致有效的证明. 这个区域则是退化问题的充分光滑解存在的区域.

二、形式渐近解

我们考察下列拟线性双曲—抛物型方程, 具有变动边界的初边值问题的奇摄动:

$$\varepsilon \frac{\partial^2 u_i}{\partial t^2} + \frac{\partial u_i}{\partial t} = A\left(x, t, u_i, \frac{\partial u_i}{\partial x}\right) \frac{\partial^2 u_i}{\partial x^2} + F\left(x, t, u_i, \frac{\partial u_i}{\partial x}\right) \quad (2.1)$$

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$$\begin{aligned} & (l_0(t) < x < l_1(t), 0 < t < T) \\ (u_\varepsilon(x, 0) = \varphi_0(x) & \quad (l_0(0) \leq x \leq l_1(0)) \end{aligned} \quad (2.2)$$

$$\frac{\partial u_\varepsilon}{\partial t}(x, 0) = \varphi_1(x) \quad (l_0(0) \leq x \leq l_1(0)) \quad (2.3)$$

$$\frac{\partial u_\varepsilon}{\partial x}(l_i(t), t) = \psi_i(t) \quad (0 \leq t \leq T), (i=0, 1) \quad (2.4)$$

其中 $0 < \varepsilon \ll 1$, 假设

(H1) $A(x, t, u, p) \geq \alpha_0 > 0$, $F'_u(x, t, u, p) \leq c_0 < 0$

(H2) 系数 $A(x, t, u, p)$ 及 $F(x, t, u, p)$ 在 $\{l_0(t) \leq x \leq l_1(t), 0 \leq t \leq T, |u| \leq M_0, |p| < +\infty\}$ 上关于所有变元为充分光滑.

(H3) 当 $0 \leq t \leq T$, $l_0(t)$, $l_1(t)$ 连续可微, 且 $l'_0(t) < l'_1(t)$, $l'_0(t) \geq 0$, $l'_1(t) \leq 0$.

(H4) $\varphi_0(x)$ 连续可微, $\varphi_1(x)$ 与 $\psi_i(t)$ ($i=0, 1$) 连续, 且 $\varphi'_0(l_0(0)) = \psi_0(0)$, $\varphi'_0(l_1(0)) = \psi_1(0)$.

迄今为止, 这样的问题, 其整体光滑解的存在性还没有一般性的结论. 因此我们限定在充分光滑解存在的局部区域上讨论. 为简单起见, 假定此区域即为 $Q = \{(x, t) | l_0(t) \leq x \leq l_1(t), 0 \leq t \leq T\}$.

当 $\varepsilon = 0$ 时, 得到退化问题:

$$\frac{\partial u_0}{\partial t} = A\left(x, t, u_0, \frac{\partial u_0}{\partial x}\right) \frac{\partial^2 u_0}{\partial x^2} + F\left(x, t, u_0, \frac{\partial u_0}{\partial x}\right) \quad (2.5)$$

$$(l_0(t) < x < l_1(t), 0 < t < T)$$

$$u_0(x, 0) = \varphi_0(x) \quad (l_0(0) \leq x \leq l_1(0)) \quad (2.6)$$

$$\frac{\partial u_0}{\partial x}(l_i(t), t) = \psi_i(t) \quad (0 \leq t \leq T), (i=0, 1) \quad (2.7)$$

显然, 这是一个拟线性抛物型方程, 具有变动边界的初边值问题. 许多文献^{[8][9]}都作过研究, 其光滑解是存在唯一的, 我们将以此解作为原问题 (2.1)~(2.4) 解的渐近展开式的首项.

首先, 我们构造问题 (2.1)~(2.4) 的形式渐近解. 设其外部解的二阶展开式为

$$u_\varepsilon = u_0 + \varepsilon u_1 + \varepsilon^2 u_2 + O(\varepsilon^3) \quad (2.8)$$

将 (2.8) 式代入方程 (2.1). 为简便起见, 记

$$A\left(x, t, u_\varepsilon, \frac{\partial u_\varepsilon}{\partial x}\right) = A(u_\varepsilon), \quad F\left(x, t, u_\varepsilon, \frac{\partial u_\varepsilon}{\partial x}\right) = F(u_\varepsilon),$$

$$A_u\left(x, t, u_\varepsilon, \frac{\partial u_\varepsilon}{\partial x}\right) = A_u(u_\varepsilon), \quad F_u\left(x, t, u_\varepsilon, \frac{\partial u_\varepsilon}{\partial x}\right) = F_u(u_\varepsilon)$$

等等, 余此类推.

由于 $A(u_\varepsilon)$, $F(u_\varepsilon)$ 的光滑性, 我们有

$$\begin{aligned} A(u_\varepsilon) &= A(u_0) + \varepsilon \left[u_1 A_u(u_0) + \frac{\partial u_1}{\partial x} A_{u'}(u_0) \right] + \varepsilon^2 \left[u_2 A_u(u_0) \right. \\ &\quad \left. + \frac{\partial u_2}{\partial x} A_{u'}(u_0) + \frac{1}{2!} u_1^2 A_{uu}(u_0) + \frac{1}{2!} 2u_1 \frac{\partial u_1}{\partial x} A_{uu'}(u_0) \right] \end{aligned}$$

$$\begin{aligned}
& + \frac{1}{2!} \left(\frac{\partial u_1}{\partial x} \right)^2 A_{u'u'}(u_0) \Big] + O(\varepsilon^3) \\
F(u_\varepsilon) = & F(u_0) + \varepsilon \left[u_1 F_u(u_0) + \frac{\partial u_1}{\partial x} F_{u'}(u_0) \right] + \varepsilon^2 \left[u_2 F_u(u_0) \right. \\
& + \frac{\partial u_2}{\partial x} F_{u'}(u_0) + \frac{1}{2!} u_1^2 F_{uu}(u_0) + \frac{1}{2!} 2u_1 \frac{\partial u_1}{\partial x} F_{uu'}(u_0) \\
& \left. + \frac{1}{2!} \left(\frac{\partial u_1}{\partial x} \right)^2 F_{u'u'}(u_0) \right] + O(\varepsilon^3)
\end{aligned}$$

将上述展开式及(2.8)代入(2.1), 并使 ε^i ($i=0,1$)的系数求和, 分别令其为零, 我们得到关于 u_0, u_1, u_2 的递推方程:

$$\frac{\partial u_0}{\partial t} = A(u_0) \frac{\partial^2 u_0}{\partial x^2} + F(u_0) \quad (2.9)$$

$$\begin{aligned}
\frac{\partial u_1}{\partial t} = & A(u_0) \frac{\partial^2 u_1}{\partial x^2} + \frac{\partial u_1}{\partial x} \left[\frac{\partial^2 u_0}{\partial x^2} A_{u'}(u_0) + F_{u'}(u_0) \right] + u_1 \left[\frac{\partial^2 u_0}{\partial x^2} A_u(u_0) \right. \\
& \left. + F_u(u_0) \right] - \frac{\partial^2 u_0}{\partial t^2} \quad (2.10)
\end{aligned}$$

$$\begin{aligned}
\frac{\partial u_2}{\partial t} = & A(u_0) \frac{\partial^2 u_2}{\partial x^2} + \frac{\partial u_2}{\partial x} \left[\frac{\partial^2 u_0}{\partial x^2} A_{u'}(u_0) + F_{u'}(u_0) \right] + u_2 \left[\frac{\partial^2 u_0}{\partial x^2} A_u(u_0) \right. \\
& \left. + F_u(u_0) \right] - \frac{\partial^2 u_1}{\partial t^2} + \frac{\partial^2 u_1}{\partial x^2} \left[u_1 A_u(u_0) + \frac{\partial u_1}{\partial x} A_{u'}(u_0) \right] + \frac{\partial^2 u_0}{\partial x^2} \\
& \cdot \left[\frac{1}{2} u_1^2 A_{uu}(u_0) + u_1 \frac{\partial u_1}{\partial x} A_{uu'}(u_0) + \frac{1}{2} \left(\frac{\partial u_1}{\partial x} \right)^2 + A_{uu'}(u_0) \right] \frac{1}{2} u_1^2 F_{uu}(u_0) \\
& + u_1 \frac{\partial u_1}{\partial x} F_{uu'}(u_0) + \frac{1}{2} \left(\frac{\partial u_1}{\partial x} \right)^2 F_{u'u'}(u_0) \quad (2.11)
\end{aligned}$$

它们的定解条件将在后面依次给出.

由于方程(2.9)~(2.11)分别为拟线性方程(2.5)及线性方程, 加上各自的定解条件(2.29a)~(2.29c), (2.31a)~(2.31c), 显然都存在光滑解(在 Q 上), 依次递推, 我们得到 u_0, u_1, u_2 , 也得到了(2.8). 一般地讲, 解(2.8)不可能再满足初值条件(2.3). 为此我们必须在 $t=0$ 附近(即所谓内部区域)构造边界层项.

设边界层项为

$$V = \varepsilon v_1 + \varepsilon^2 v_2 + O(\varepsilon^3) \quad (2.12)$$

记 $U = u_0 + \varepsilon u_1 + \varepsilon^2 u_2$, 将 $U+V$ 代入方程(2.1), 由于(2.9)~(2.11), 得

$$\begin{aligned}
\varepsilon \frac{\partial^2 V}{\partial t^2} + \frac{\partial V}{\partial t} = & A(U) \frac{\partial^2 V}{\partial x^2} + \left[A(U+V) - A(U) \right] \left[\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 V}{\partial x^2} \right] \\
& + F(U+V) - F(U) + O(\varepsilon^3) \quad (2.13)
\end{aligned}$$

将 $A(U), A(U+V) - A(U), F(U+V) - F(U)$ 展开为 ε 的幂级数形式,

$$\begin{aligned}
A(U) = & A(u_0) + \varepsilon \left[u_1 A_u(u_0) + \frac{\partial u_1}{\partial x} A_{u'}(u_0) \right] + \varepsilon^2 \left[u_2 A_u(u_0) + \frac{\partial u_2}{\partial x} A_{u'}(u_0) \right. \\
& \left. + \frac{1}{2!} u_1^2 A_{uu}(u_0) + \frac{1}{2!} 2u_1 \frac{\partial u_1}{\partial x} A_{uu'}(u_0) + \frac{1}{2!} \left(\frac{\partial u_1}{\partial x} \right)^2 A_{u'u'}(u_0) \right] + O(\varepsilon^3) \quad (2.14)
\end{aligned}$$

$$\begin{aligned}
A(U+V) - A(U) = & \varepsilon \left[v_1 A_u(u_0) + \frac{\partial v_1}{\partial x} A_{u'}(u_0) \right] + \varepsilon^2 \left[u_1 v_1 A_{uu}(u_0) \right. \\
& + \frac{\partial u_1}{\partial x} v_1 A_{uu'}(u_0) + u_1 \frac{\partial v_1}{\partial x} A_{u'u}(u_0) + \frac{\partial u_1}{\partial x} \frac{\partial v_1}{\partial x} A_{u'u'}(u_0) + v_2 A_u(u_0) \\
& + \frac{\partial v_2}{\partial x} A_{u'}(u_0) + \frac{1}{2} v_1^2 A_{uu}(u_0) + v_1 \frac{\partial v_1}{\partial x} A_{uu'}(u_0) + \frac{1}{2} \left(\frac{\partial v_1}{\partial x} \right)^2 A_{u'u'}(u_0) \left. \right] \\
& + O(\varepsilon^3)
\end{aligned} \tag{2.15}$$

$$\begin{aligned}
F(U+V) - F(U) = & \varepsilon \left[v_1 F_u(u_0) + \frac{\partial v_1}{\partial x} F_{u'}(u_0) \right] + \varepsilon^2 \left[u_1 v_1 F_{uu}(u_0) \right. \\
& + \frac{\partial u_1}{\partial x} v_1 F_{uu'}(u_0) + u_1 \frac{\partial v_1}{\partial x} F_{u'u}(u_0) + \frac{\partial u_1}{\partial x} \frac{\partial v_1}{\partial x} F_{u'u'}(u_0) + v_2 F_u(u_0) \\
& + \frac{\partial v_2}{\partial x} F_{u'}(u_0) + \frac{1}{2} v_1^2 F_{uu}(u_0) + v_1 \frac{\partial v_1}{\partial x} F_{uu'}(u_0) + \frac{1}{2} \left(\frac{\partial v_1}{\partial x} \right)^2 \\
& \cdot F_{u'u'}(u_0) \left. \right] + O(\varepsilon^3)
\end{aligned} \tag{2.16}$$

引进伸展变量并应用两变量展开直接构造边界层^[6],

$$\xi = \frac{t}{\varepsilon}, \quad \eta = t, \quad x = x \tag{2.17}$$

$$\therefore \frac{\partial}{\partial t} = \frac{\partial}{\partial \eta} + \frac{1}{\varepsilon} \frac{\partial}{\partial \xi}; \quad \frac{\partial^2}{\partial t^2} = \frac{\partial^2}{\partial \eta^2} + 2 \frac{1}{\varepsilon} \frac{\partial^2}{\partial \xi \partial \eta} + \frac{1}{\varepsilon^2} \frac{\partial^2}{\partial \xi^2} \tag{2.18}$$

将(2.14)~(2.18)代入(2.13), 得到

$$\begin{aligned}
& \left(\frac{\partial^2 v_1}{\partial \xi^2} + \frac{\partial v_1}{\partial \xi} \right) + \varepsilon \left(\frac{\partial^2 v_2}{\partial \xi^2} + \frac{\partial v_2}{\partial \xi} + 2 \frac{\partial^2 v_1}{\partial \xi \partial \eta} + \frac{\partial v_1}{\partial \eta} \right) + \varepsilon^2 \left(\frac{\partial v_2}{\partial \eta} + \frac{\partial^2 v_1}{\partial \eta^2} + 2 \frac{\partial^2 v_2}{\partial \xi \partial \eta} \right) + \varepsilon^3 \frac{\partial^2 v_2}{\partial \eta^2} \\
& = \varepsilon \left\{ \frac{\partial^2 v_1}{\partial x^2} A(u_0) + \frac{\partial v_1}{\partial x} \left[\frac{\partial^2 u_0}{\partial x^2} A_{u'}(u_0) + F_{u'}(u_0) \right] + v_1 \left[\frac{\partial^2 u_0}{\partial x^2} \right. \right. \\
& \quad \left. \left. \cdot A_u(u_0) + F_u(u_0) \right] \right\} + O(\varepsilon^2)
\end{aligned} \tag{2.19}$$

由此我们得到了关于 v_1, v_2 的递推方程

$$\frac{\partial^2 v_1}{\partial \xi^2} + \frac{\partial v_1}{\partial \xi} = 0 \tag{2.20}$$

$$\begin{aligned}
\frac{\partial^2 v_2}{\partial \xi^2} + \frac{\partial v_2}{\partial \xi} = & -2 \frac{\partial^2 v_1}{\partial \xi \partial \eta} - \frac{\partial v_1}{\partial \eta} + \frac{\partial^2 v_1}{\partial x^2} A(u_0) + \frac{\partial v_1}{\partial x} \left[\frac{\partial^2 u_0}{\partial x^2} A_{u'}(u_0) \right. \\
& \left. + F_{u'}(u_0) \right] + v_1 \left[\frac{\partial^2 u_0}{\partial x^2} A_u(u_0) + F_u(u_0) \right]
\end{aligned} \tag{2.21}$$

显然, 方程(2.20)有指数型衰减的解

$$v_1 = P_1(x, \eta) e^{-\xi} \tag{2.22}$$

其中 P_1 为满足下列方程的解.

$$\frac{\partial P_1}{\partial \eta} = A(u_0) \frac{\partial^2 P_1}{\partial x^2} + \frac{\partial P_1}{\partial x} \left[\frac{\partial^2 u_0}{\partial x^2} A_{u'}(u_0) + F_{u'}(u_0) \right] + P_1 \left[\frac{\partial^2 u_0}{\partial x^2} A_u(u_0) + F_u(u_0) \right] \tag{2.23}$$

其定解条件为(2.30a)、(2.31a). 由于(2.22)、(2.23), 方程(2.21)化简为

$$\frac{\partial^2 v_2}{\partial \xi^2} + \frac{\partial v_2}{\partial \xi} = 2 \frac{\partial P_1}{\partial \eta} e^{-\xi} \tag{2.21}'$$

显然, 方程(2.21)'也有指数型衰减的解,

$$v_2 = P_2(x, \eta) e^{-\xi} - 2 \frac{\partial P_1}{\partial \eta} \xi e^{-\xi} \quad (2.24)$$

其中 P_2 为只要满足条件(2.30b), (2.31c)的, 对 x, η 为适当光滑的任意函数. 这样我们得到了在 Q 中解 u_ε 的形式渐近展开式,

$$u_\varepsilon = u_0 + \varepsilon u_1 + \varepsilon^2 u_2 + \varepsilon v_1 + \varepsilon^2 v_2 + O(\varepsilon^3) \quad (2.25)$$

用 Z 记为其余项,

$$\therefore u_\varepsilon = U + V + Z \quad (2.26)$$

下面我们来确定递推方程(2.9)、(2.10)、(2.11)和(2.20)、(2.21)、(2.23)的初边值条件.

初始条件

$$\therefore u_\varepsilon(x, 0) = [u_0 + \varepsilon(u_1 + v_1) + \varepsilon^2(u_2 + v_2) + O(\varepsilon^3)]_{t=0} = \varphi_0(x)$$

$$\begin{aligned} \frac{\partial u_\varepsilon}{\partial t}(x, 0) = & \left[\frac{\partial u_0}{\partial t} + \frac{\partial v_1}{\partial \xi} + \varepsilon \left(\frac{\partial u_1}{\partial t} + \frac{\partial v_2}{\partial \xi} + \frac{\partial v_1}{\partial \eta} \right) + \varepsilon^2 \left(\frac{\partial u_2}{\partial t} + \frac{\partial v_2}{\partial \eta} \right) \right. \\ & \left. + O(\varepsilon^3) \right]_{t=0} = \varphi_1(x) \end{aligned}$$

$$\therefore u_0(x, 0) = \varphi_0(x) \quad (2.27a)$$

$$u_1(x, 0) = -v_1(x, 0, 0) \quad (2.27b)$$

$$u_2(x, 0) = -v_2(x, 0, 0) \quad (2.27c)$$

$$\frac{\partial v_1}{\partial \xi}(x, 0, 0) = \varphi_1(x) - \frac{\partial u_0}{\partial t}(x, 0) \quad (2.28a)$$

$$\frac{\partial v_2}{\partial \xi}(x, 0, 0) = -\frac{\partial u_1}{\partial t}(x, 0) - \frac{\partial v_2}{\partial \eta}(x, 0, 0) \quad (2.28b)$$

再根据 v_1, v_2 的具体表达式, 上述条件化为

$$u_0(x, 0) = \varphi_0(x) \quad (2.29a)$$

$$u_1(x, 0) = \varphi_1(x) - \frac{\partial u_0}{\partial t}(x, 0) \quad (2.29b)$$

$$u_2(x, 0) = \frac{\partial P_1}{\partial \eta}(x, 0) - \frac{\partial u_1}{\partial t}(x, 0) \quad (2.29c)$$

$$P_1(x, 0) = \frac{\partial u_0}{\partial \eta}(x, 0) - \varphi_1(x) \quad (2.30a)$$

$$P_2(x, 0) = \frac{\partial u_1}{\partial \eta}(x, 0) - \frac{\partial P_1}{\partial \eta}(x, 0) \quad (2.30b)$$

边界条件

在边界上可以导出下列条件,

$$\frac{\partial u_0}{\partial x}(l_i(t), t) = \psi_i(t) \quad (i=0, 1) \quad (3.31a)$$

$$\frac{\partial u_1}{\partial x}(l_i(t), t) = \frac{\partial P_1}{\partial x}(l_i(t), t) = 0 \quad (i=0, 1) \quad (3.31b)$$

$$\frac{\partial u_2}{\partial x}(l_i(t), t) = \frac{\partial P_2}{\partial x}(l_i(t), t) = 0 \quad (i=0, 1) \quad (3.31c)$$

根据上述初边值条件的特点, 关于 u_0, u_1, u_2 与 v_1, v_2 的递推求解应当按 u_0, u_1, v_1, u_2, v_2 的次序交替进行.

三、余项的估计

容易发现余项 Z 满足下面的方程与条件,

$$\begin{aligned} \varepsilon \frac{\partial^2 Z}{\partial t^2} + \frac{\partial Z}{\partial t} - A(U+V+Z) \frac{\partial^2 Z}{\partial x^2} + \frac{\partial^2(U+V)}{\partial x^2} \left[ZA_u(U+V+\theta_1 Z) \right. \\ \left. + \frac{\partial Z}{\partial x} A_{u'}(U+V+\theta_2 Z) \right] + \left[ZF_u(U+V+\theta_3 Z) + \frac{\partial Z}{\partial x} F_{u'}(U+V+\theta_4 Z) \right] \\ = g(x, t, \varepsilon) \end{aligned} \quad (3.1)$$

$$Z(x, 0) = 0 \quad (3.2)$$

$$\frac{\partial Z}{\partial t}(x, 0) = O(\varepsilon^2) \quad (3.3)$$

$$\frac{\partial Z}{\partial x}(l_i(t), t) = 0 \quad (i=0, 1) \quad (3.4)$$

其中, $0 < \theta_i < 1$ ($i=1, 2, 3, 4$), 而 $g(x, t, \varepsilon) = O(\varepsilon^2)$. 为方便计, 如文[5]将(3.3)改为 $\partial Z(x, 0) / t = 0$, 这种改变并不影响在 ε^2 量级上对 Z 的估计.

记 $Q_t = \{(x, t) \mid l_0(t) \leq x \leq l_1(t), 0 \leq t \leq \bar{t} < T\}$. 方程(3.1)的两边同乘以 $2\partial Z / \partial t$ 并在 Q_t 上积分之.

$$\begin{aligned} 2 \int_{Q_t} \left(\frac{\partial Z}{\partial t} \right)^2 dQ + \varepsilon \int_{Q_t} 2 \frac{\partial Z}{\partial t} \left(\frac{\partial^2 Z}{\partial t^2} \right) dQ - 2 \int_{Q_t} A(U+V+Z) \frac{\partial^2 Z}{\partial x^2} \frac{\partial Z}{\partial t} dQ \\ - 2 \int_{Q_t} Z \frac{\partial Z}{\partial t} \left[A_u(U+V+\theta_1 Z) \frac{\partial^2(U+V)}{\partial x^2} + F_u(U+V+\theta_3 Z) \right] dQ \\ - 2 \int_{Q_t} \frac{\partial Z}{\partial t} \frac{\partial Z}{\partial x} \left[A_{u'}(U+V+\theta_2 Z) \frac{\partial^2(U+V)}{\partial x^2} + F_{u'}(U+V+\theta_4 Z) \right] dQ \\ = 2 \int_{Q_t} \frac{\partial Z}{\partial t} g(x, t, \varepsilon) dQ \end{aligned} \quad (3.5)$$

其中

$$\begin{aligned} \text{(I)} \quad \varepsilon \int_{Q_t} 2 \frac{\partial Z}{\partial t} \left(\frac{\partial^2 Z}{\partial t^2} \right) dQ = \varepsilon \int_{Q_t} \frac{\partial}{\partial t} \left(\frac{\partial Z}{\partial t} \right)^2 dx dt = \varepsilon \int_{l_0(\bar{t})}^{l_0(\bar{t})} \left(\frac{\partial Z}{\partial t} \right)^2 \Big|_{t=l_0^{-1}(x)} dx \\ + \varepsilon \int_{l_0(\bar{t})}^{l_1(\bar{t})} \left(\frac{\partial Z}{\partial t} \right)^2 \Big|_{t=\bar{t}} dx + \varepsilon \int_{l_1(\bar{t})}^{l_1(0)} \left(\frac{\partial Z}{\partial t} \right)^2 \Big|_{t=l_1^{-1}(x)} dx \geq 0 \end{aligned}$$

$$\begin{aligned} \text{(II)} \quad 2 \int_{Q_t} A(U+V+Z) \frac{\partial^2 Z}{\partial x^2} \frac{\partial Z}{\partial t} dQ = 2 \int_{Q_t} \left[\frac{\partial}{\partial x} \left(A \frac{\partial Z}{\partial x} \frac{\partial Z}{\partial t} \right) \right. \\ \left. - \frac{\partial A}{\partial x} \frac{\partial Z}{\partial x} \frac{\partial Z}{\partial t} - \frac{1}{2} A \frac{\partial}{\partial t} \left(\frac{\partial Z}{\partial x} \right)^2 \right] dQ \\ = -2 \int_{Q_t} \frac{\partial A}{\partial x} \frac{\partial Z}{\partial x} \frac{\partial Z}{\partial t} dQ - \int_{l_0(\bar{t})}^{l_1(\bar{t})} A \left(\frac{\partial Z}{\partial x} \right)^2 \Big|_{t=\bar{t}} dx + \int_{Q_t} \frac{\partial A}{\partial t} \left(\frac{\partial Z}{\partial x} \right)^2 dQ \end{aligned}$$

$$\begin{aligned}
(\text{II}) \quad & 2 \int_{Q_t} Z \frac{\partial Z}{\partial t} \left[A_u(U+V+\theta_1 Z) \frac{\partial^2(U+V)}{\partial x^2} + F_u(U+V+\theta_2 Z) \right] dQ \\
& = \int_{Q_t} \frac{\partial Z^2}{\partial t} \left[A_u(U+V+\theta_1 Z) \frac{\partial^2(U+V)}{\partial x^2} + F_u(U+V+\theta_2 Z) \right] dQ \\
& = \int_{l_0(\bar{t})}^{l_0(\bar{t})} Z^2 \left[A_u(\cdot) \frac{\partial^2(U+V)}{\partial x^2} + F_u(\cdot) \right]_{t=l_0^{-1}(x)} dx + \int_{l_0(\bar{t})}^{l_1(\bar{t})} Z^2 \left[A_u(\cdot) \right. \\
& \quad \cdot \left. \frac{\partial^2(U+V)}{\partial x^2} + F_u(\cdot) \right]_{t=\bar{t}} dx + \int_{l_1(\bar{t})}^{l_1(0)} Z^2 \left[A_u(\cdot) \frac{\partial^2(U+V)}{\partial x^2} \right. \\
& \quad \left. + F_u(\cdot) \right]_{t=l_1^{-1}(x)} dx - \int_{Q_t} Z^2 \frac{\partial}{\partial t} \left[A_u(\cdot) \frac{\partial^2(U+V)}{\partial x^2} + F_u(\cdot) \right] dQ
\end{aligned}$$

其中, $A_u(\cdot) = A_u(U+V+\theta_1 Z)$, $F_u(\cdot) = F_u(U+V+\theta_2 Z)$, $A = A(U+V+Z)$

记 $A_u'(\cdot) = A_u'(U+V+\theta_1 Z)$, $F_u'(\cdot) = F_u'(U+V+\theta_2 Z)$

$$\begin{aligned}
\therefore \quad & 2 \int_{Q_t} \left(\frac{\partial Z}{\partial t} \right)^2 dQ + \int_{l_0(\bar{t})}^{l_1(\bar{t})} A \left(\frac{\partial Z}{\partial x} \right)^2 \Big|_{t=\bar{t}} dx - \int_{l_0(\bar{t})}^{l_1(\bar{t})} Z^2 F_u(\cdot) \Big|_{t=\bar{t}} dx \\
& + 2 \int_{Q_t} \frac{\partial Z}{\partial x} \frac{\partial Z}{\partial t} \left[\frac{\partial A}{\partial x} - A_u'(\cdot) \frac{\partial^2(U+V)}{\partial x^2} - F_u'(\cdot) \right] dQ + \int_{Q_t} Z^2 \frac{\partial}{\partial t} \left[A_u(\cdot) \right. \\
& \quad \cdot \left. \frac{\partial^2(U+V)}{\partial x^2} + F_u(\cdot) \right] dQ - \int_{Q_t} \frac{\partial A}{\partial t} \left(\frac{\partial Z}{\partial x} \right)^2 dQ - \int_{l_0(0)}^{l_0(\bar{t})} Z^2 \left[A_u(\cdot) \right. \\
& \quad \cdot \left. \frac{\partial^2(U+V)}{\partial x^2} + F_u(\cdot) \right]_{t=l_0^{-1}(x)} dx - \int_{l_1(\bar{t})}^{l_1(0)} Z^2 \left[A_u(\cdot) \frac{\partial^2(U+V)}{\partial x^2} \right. \\
& \quad \left. + F_u(\cdot) \right]_{t=l_1^{-1}(x)} dx - \int_{l_0(\bar{t})}^{l_1(\bar{t})} Z^2 A_u(\cdot) \frac{\partial^2(U+V)}{\partial x^2} \Big|_{t=\bar{t}} dx \\
& \leq 2 \int_{Q_t} \frac{\partial Z}{\partial t} g(x, t, \varepsilon) dQ
\end{aligned}$$

$$\begin{aligned}
\therefore \quad & 2 \int_{Q_t} \left(\frac{\partial Z}{\partial t} \right)^2 dQ + \min(a_0, -c_0) \int_{l_0(\bar{t})}^{l_1(\bar{t})} \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 \right]_{t=\bar{t}} dx \\
& \leq M_1 \int_{Q_t} \left| \frac{\partial Z}{\partial x} \frac{\partial Z}{\partial t} \right| dQ + M_2 \int_{Q_t} Z^2 dQ \\
& \quad + M_3 \int_{Q_t} \left(\frac{\partial Z}{\partial x} \right)^2 dQ + M_4 \left\{ \int_{l_0(0)}^{l_0(\bar{t})} Z^2 \Big|_{t=l_0^{-1}(x)} dx \right. \\
& \quad \left. + \int_{l_0(\bar{t})}^{l_1(\bar{t})} Z^2 \Big|_{t=\bar{t}} dx + \int_{l_1(\bar{t})}^{l_1(0)} Z^2 \Big|_{t=l_1^{-1}(x)} dx \right\} + 2 \int_{Q_t} \frac{\partial Z}{\partial t} g(x, t, \varepsilon) dQ
\end{aligned}$$

其中由于 $Z(x, 0) = 0$, $\therefore M_4 \{\dots\} = M_4 \int_{Q_t} \frac{\partial Z^2}{\partial t} dQ = 2M_4 \int_{Q_t} Z \frac{\partial Z}{\partial t} dQ$

我们可以选取 λ, μ, ν 足够小, 使 $(2 - M_1\lambda - 2M_4\mu - 2\nu) > 0$.

$$\begin{aligned}
\therefore \quad & (2 - M_1\lambda - 2M_4\mu - 2\nu) \int_{Q_t} \left(\frac{\partial Z}{\partial t} \right)^2 dQ + \min(a_0, -c_0) \int_{l_0(\bar{t})}^{l_1(\bar{t})} \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 \right]_{t=\bar{t}} dx \\
& \leq \frac{M_1}{\lambda} \int_{Q_t} \left(\frac{\partial Z}{\partial x} \right)^2 dQ + M_2 \int_{Q_t} Z^2 dQ + M_3 \int_{Q_t} \left(\frac{\partial Z}{\partial x} \right)^2 dQ + \frac{2M_0}{\mu} \int_{Q_t} Z^2 dQ
\end{aligned}$$

$$+ \frac{2}{\nu} \int_{Q_t} g^2(x, t, \varepsilon) dQ$$

记 $K = \min(a_0, -c_0)$, $M = \max\left(\frac{M_1}{\lambda} + M_3, M_2 + \frac{2M_4}{\mu}\right)$, $N = \frac{2}{\nu}$

$$\therefore K \int_{l_0(\bar{t})}^{l_1(\bar{t})} \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 \right] \Big|_{t=\bar{t}} dx \leq M \int_{Q_t} \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 \right] dQ + N \int_{Q_t} g^2(x, t, \varepsilon) dQ \quad (3.6)$$

记 $E(t) = \int_{Q_t} \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 \right] dQ$, $F(t) = \int_{Q_t} g^2(x, t, \varepsilon) dQ$

上述不等式可以写为

$$K \frac{dE(t)}{dt} \leq ME(t) + NF(t)$$

$$\therefore E(t) \leq \frac{Nt}{K} F(t) \exp\left[\frac{M}{K}t\right]$$

取 $C = \frac{NT}{K} \exp\left[\frac{M}{K}T\right]$

$$\therefore E(T) = \int_Q \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 \right] dQ \leq C \int_Q g^2(x, t, \varepsilon) dQ \quad (3.7)$$

记 $\bar{C} = C + (MC + N) / (2 - M_1\lambda - 2M_4\mu - 2\nu)$, 不难推得

$$\int_Q \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 + \left(\frac{\partial Z}{\partial t} \right)^2 \right] dQ \leq \bar{C} \int_Q g^2(x, t, \varepsilon) dQ \quad (3.8)$$

$$\therefore \|Z\| = \left\{ \int_Q \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 + \left(\frac{\partial Z}{\partial t} \right)^2 \right] dQ \right\}^{1/2} = O(\varepsilon^2) \quad (3.9)$$

最后, 我们得到如下的定理.

定理 对于拟线性双曲-抛物型方程, 具有变动边界的初边值问题(2.1)~(2.4), 当假设(H1)~(H4)满足, 且 ε 充分小时, 则在存在充分光滑解的区域 $Q = \{(x, t) | l_0(t) \leq x \leq l_1(t), 0 \leq t \leq T\}$ 中, 具有一致有效的广义渐近解

$$u_\varepsilon = u_0 + \varepsilon u_1 + \varepsilon^2 u_2 + \varepsilon v_1 + \varepsilon^2 v_2 + Z \quad (3.10)$$

其中 u_0 为退化问题的充分光滑解, v_1, v_2 为边界层校正项 (在 $t=0$ 的邻域中). 对于余项 Z , 则在区域 Q 上一致成立下面的估计式

$$\|Z\| = \left\{ \int_Q \left[Z^2 + \left(\frac{\partial Z}{\partial x} \right)^2 + \left(\frac{\partial Z}{\partial t} \right)^2 \right] dQ \right\}^{1/2} = O(\varepsilon^2) \quad (3.11)$$

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On Singular Perturbation for a Nonlinear initial-Boundary Value Problem (II)

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Abstract

In this paper, we consider a singularly perturbed problem of a kind of quasilinear hyperbolic-parabolic equations, subject to initial-boundary value conditions with moving boundary:

$$\varepsilon \frac{\partial^2 u_\varepsilon}{\partial t^2} + \frac{\partial u_\varepsilon}{\partial t} = A\left(x, t, u_\varepsilon, \frac{\partial u_\varepsilon}{\partial x}\right) \frac{\partial^2 u_\varepsilon}{\partial x^2} + F\left(x, t, u_\varepsilon, \frac{\partial u_\varepsilon}{\partial x}\right)$$

$$u_\varepsilon(x, 0) = \varphi_0(x), \quad \frac{\partial u_\varepsilon}{\partial t}(x, 0) = \varphi_1(x); \quad \frac{\partial u_\varepsilon}{\partial x}(l_i(t), t) = \psi_i(t) \quad (i=0, 1)$$

When certain assumptions are satisfied and ε is sufficiently small, the solution of this problem has a generalized asymptotic expansion (in the Van der Corput sense), which takes the sufficiently smooth solution of the reduced problem as the first term, and is uniformly valid in domain Q where the sufficiently smooth solution exists. The layer exists in the neighborhood of $t=0$. This paper is the development of references [3]~[5].

Key words singular perturbation, moving boundary, asymptotic expansion