

# 具有不等厚表层的夹层旋转壳问题

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## 摘 要

本文探讨了具有各向同性夹心及不等厚表层组成的三层旋转壳的小挠度问题, 采用广义变分法, 在考虑表层抗弯刚度的情况下, 导出了基本方程, 其特例即为文献 [3], [4] 的结果.

根据所导出的基本方程, 本文求解对称加载的夹层旋转壳问题, 将其归结为只含一个广义位移的六阶微分方程.

本文的理论可应用于复合装甲及其它工程设计.

## 一、引 言

近年来, 由于夹层板壳结构具有重量轻、强度高、刚度大等特点, 因而在航空、船舶制造、宇航等部门受到了愈来愈大的重视, 钱伟长<sup>[9]</sup>早就对板壳理论作出了巨大贡献.

对于夹层结构的强度、刚度、稳定性及热效应、动应力等, 国内外已进行了广泛的研究, 不少人提出了各种计算模型. 就线性理论而言, 早期由 Reissner<sup>[6]</sup>提出的夹层板理论较为简单实用. 他把表板看作薄膜, 而忽略其抗弯刚度, 并认为夹心只承受抗剪作用. 对于许多工程问题, 这种模型已具有足够的精度.

Hoff<sup>[7]</sup>提出的夹层板理论, 不仅考虑夹心的横向剪切变形, 还考虑了表板的抗弯刚度, 从而解决了一些用 Reissner 理论不能求解的问题.

由于 Reissner 和 Hoff 的理论中基本方程的复杂性, 难以求解实际问题, 胡海昌<sup>[2]</sup>将 Reissner 理论的基本方程归结为求解两个位移函数的微分方程, 从而为解决具体问题提供了方便的途径.

此后, 由 Прусаков<sup>[8]</sup>、杜庆华<sup>[1]</sup>提出的夹层板理论指出, 夹层板中除了反对称型的弯曲变形, 还存在对称型弯曲. 他们除了考虑表板的抗弯作用和夹心的抗剪作用外, 还考虑了夹心的横向弹性变形.

近来, 中国科学院北京力学所板壳组<sup>[3]</sup>对于夹层板壳问题出版了专著, 阐明了有关夹层板壳的各种理论问题和实际问题, 并提供了简化计算的方法.

最近, 文献 [4] 将 Hoff 的夹层板理论推广到了具有不等厚表板的夹层板. 本文进一步研究了具有不等厚表层的夹层旋转壳问题, 采用广义变分法, 在考虑表层抗弯刚度的情况下导出了基本方程, 并由此求解对称加载的夹层旋转壳问题, 将它归结为只含一个广义位移的六阶微分方程.

## 二、基本方程的推导

图 1 表示具有不等厚表层的夹层旋转壳。夹心及表层壳都是由各向同性材料制成。夹心“c”较软； $\gamma$  为正的一侧为外表层，用“+”表示； $\gamma$  为负的一侧为内表层，用“-”表示；其厚度分别为  $t_1, t_2$ ；外载荷  $p^\pm$  以沿  $\gamma$  方向作用为正。

本文采用正交曲线坐标，以 1, 2, 3 分别表示三个坐标方向的应力应变分量。

本文采用下述假定：(1) 内外表层壳作为薄壳处理；(2) 由于夹心较软，故忽略夹心中平行于  $\alpha\beta$  坐标面的应力分量，即假定  $\sigma_1^c = \sigma_2^c = \tau_{12}^c = 0$ ；(3) 不计夹心的横向弹性，即认为  $\epsilon_3^c = 0$ ，又因  $\sigma_3^c$  甚小，故认为  $\sigma_3^c = 0$ ；

上述假定通常不会影响工程应用中的精度要求。

### 1. 平衡方程的推导

设夹层旋转壳中面在  $\alpha, \beta$  方向的曲率半径为  $R_1, R_2$ ，它们只是  $\alpha$  的函数，其 Lamé 系数分别为  $R_1, R_2 \sin \alpha$ ，Gauss 条件为

$$\frac{d}{d\alpha}(R_2 \sin \alpha) = R_1 \cos \alpha \tag{2.1}$$

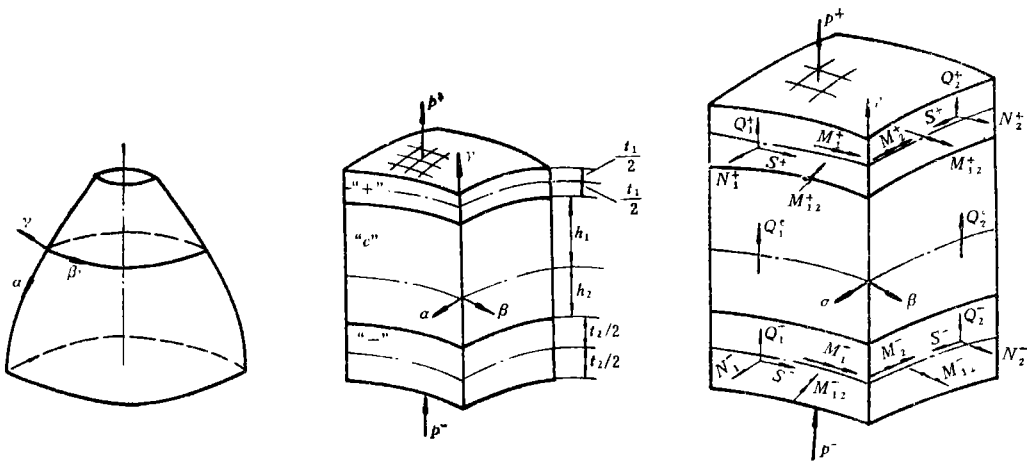


图 1

图 2

内外表层壳及夹心的内力如图 2 所示。内力-应变关系为：

$$\left. \begin{aligned} N_1^+ &= B_1(\epsilon_1^+ + \mu\epsilon_2^+), & N_2^+ &= B_1(\epsilon_2^+ + \mu\epsilon_1^+) \\ S^+ &= \frac{1}{2}(1-\mu)B_1\epsilon_{12}^+, & M_1^+ &= D_1(\chi_1^+ + \mu\chi_2^+) \\ M_2^+ &= D_1(\chi_2^+ + \mu\chi_1^+), & M_{12}^+ &= D_1(1-\mu)\chi_{12}^+ \\ N_1^- &= B_2(\epsilon_1^- + \mu\epsilon_2^-), & N_2^- &= B_2(\epsilon_2^- + \mu\epsilon_1^-) \\ S^- &= \frac{1}{2}(1-\mu)B_2\epsilon_{12}^-, & M_1^- &= D_2(\chi_1^- + \mu\chi_2^-) \\ M_2^- &= D_2(\chi_2^- + \mu\chi_1^-), & M_{12}^- &= D_2(1-\mu)\chi_{12}^- \end{aligned} \right\} \tag{2.2a~l}$$

其中

$$B_i = \frac{E t_i}{1 - \mu^2}; \quad D_i = \frac{E t_i^3}{12(1 - \mu^2)};$$

( $i = 1, 2$ )  $\mu$  为泊松比

应变-位移关系是

$$\left. \begin{aligned} e_1^\pm &= \varepsilon_1^\pm + \nu \chi_1^\pm \\ e_2^\pm &= \varepsilon_2^\pm + \nu \chi_2^\pm \\ e_{12}^\pm &= \varepsilon_{12}^\pm + \nu \chi_{12}^\pm \end{aligned} \right\} \quad (2.3a, b, c)$$

其中

$$\left. \begin{aligned} \varepsilon_1^\pm &= \frac{1}{R_1} \left( \frac{\partial u^\pm}{\partial \alpha} + w^\pm \right) \\ \varepsilon_2^\pm &= \frac{1}{R_2} \left( \frac{1}{\sin \alpha} \frac{\partial v^\pm}{\partial \beta} + \operatorname{ctg} \alpha \cdot u^\pm + w^\pm \right) \\ \varepsilon_{12}^\pm &= \frac{1}{R_2 \sin \alpha} \frac{\partial u^\pm}{\partial \beta} + \frac{R_2 \sin \alpha}{R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{v^\pm}{R_2 \sin \alpha} \right) \\ \chi_1^\pm &= - \frac{1}{R_1} \frac{\partial}{\partial \alpha} \left( \frac{1}{R_1} \frac{\partial w^\pm}{\partial \alpha} - \frac{u^\pm}{R_1} \right) \\ \chi_2^\pm &= - \frac{1}{R_2^2 \sin^2 \alpha} \frac{\partial^2 w^\pm}{\partial \beta^2} - \frac{\operatorname{ctg} \alpha}{R_1 R_2} \left( \frac{\partial w^\pm}{\partial \alpha} - u^\pm \right) + \frac{1}{R_2^2 \sin \alpha} \cdot \frac{\partial v^\pm}{\partial \beta} \\ \chi_{12}^\pm &= - \frac{1}{R_1 R_2 \sin \alpha} \left( \frac{\partial^2 w^\pm}{\partial \alpha \partial \beta} - \frac{R_1 \operatorname{ctg} \alpha}{R_2} \frac{\partial w^\pm}{\partial \beta} \right) \\ &\quad + \frac{1}{2} \cdot \frac{1}{R_1 R_2 \sin \alpha} \cdot \frac{\partial u^\pm}{\partial \beta} + \frac{1}{2} \cdot \frac{R_2 \sin \alpha}{R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{v^\pm}{R_2^2 \sin \alpha} \right) \end{aligned} \right\} \quad (2.4a \sim f)$$

对于夹层旋转壳有五个独立的广义位移:

$$\left. \begin{aligned} u &= \frac{B_1 u^+ + B_2 u^-}{B_1 + B_2} \\ v &= \frac{B_1 v^+ + B_2 v^-}{B_1 + B_2} \\ \psi_\alpha &= \frac{1}{k} (u^+ - u^-) \\ \psi_\beta &= \frac{1}{k} (v^+ - v^-) \\ w &= w^+ = w^- = w^c \end{aligned} \right\} \quad (2.5a \sim e)$$

此处  $k = h_1 + h_2 + \frac{1}{2}(t_1 + t_2)$

有十四个独立的广义力:

$$\left. \begin{aligned}
 N_i &= N_i^+ + N_i^- & (i=1, 2) \\
 M_i &= M_i^+ + M_i^- \\
 S &= S^+ + S^- \\
 M_{i2} &= M_{i2}^+ + M_{i2}^- \\
 M_1^i &= \frac{k}{B_1 + B_2} \cdot (B_2 N_1^+ - B_1 N_1^-) \\
 M_2^i &= \frac{k}{B_1 + B_2} \cdot (B_2 N_2^+ - B_1 N_2^-) \\
 M_{12}^i &= \frac{k}{B_1 + B_2} \cdot (B_2 S^+ - B_1 S^-) \\
 M_1^i &= \frac{1}{2} (M_1^+ - M_1^-) \\
 M_2^i &= \frac{1}{2} (M_2^+ - M_2^-) \\
 M_{12}^i &= \frac{1}{2} (M_{12}^+ - M_{12}^-)
 \end{aligned} \right\} (2.6a \sim j)$$

此外还有  $Q_1^i$  和  $Q_2^i$ ;

可导出的位移有  $u^o$  和  $v^o$ , 可导出的内力有  $Q_1^i$  和  $Q_2^i$ .

在以下计算中设  $R_1 \gg k$ ,  $R_2 \gg k$ , 故忽略  $\frac{k}{R_1}$  及  $\frac{k}{R_2}$  阶微量.

由假设 (2.2)、(2.3) 可知夹心微元的平衡方程为

$$\frac{\partial \tau_{13}^i}{\partial \gamma} = 0, \quad \frac{\partial \tau_{23}^i}{\partial \gamma} = 0 \quad (2.7)$$

可见夹心中的剪应力沿  $\gamma$  方向均匀分布, 即:

$$\tau_{13}^i = \frac{Q_1^i}{h_1 + h_2}; \quad \tau_{23}^i = \frac{Q_2^i}{h_1 + h_2} \quad (2.8)$$

夹心中的应力-应变关系为

$$\tau_{13}^o = G^o e_{13}^o, \quad \tau_{23}^o = G^o e_{23}^o \quad (2.9)$$

此处  $G^o$  为夹心的剪切弹性模量.

夹心的应变-位移关系是:

$$\left. \begin{aligned}
 e_{13}^o &= \frac{\partial u^o}{\partial \gamma} + \frac{1}{R_1} \frac{\partial w}{\partial \alpha} - \frac{u^o}{R_1} \\
 e_{23}^o &= \frac{\partial v^o}{\partial \gamma} + \frac{1}{R_2 \sin \alpha} \cdot \frac{\partial w}{\partial \beta} - \frac{v^o}{R_2}
 \end{aligned} \right\} (2.10a, b)$$

将 (2.10)、(2.9) 式代入 (2.7) 式可见:

$$\frac{\partial^2 u^o}{\partial \gamma^2} = 0, \quad \frac{\partial^2 v^o}{\partial \gamma^2} = 0 \quad (2.11)$$

即  $u^o$ ,  $v^o$  是  $\gamma$  的线性函数, 如果注意到:

$$\left. \begin{aligned} \text{在 } \gamma = h_1 \text{ 处: } & u^{\circ+} = u^+ + \frac{t_1}{2R_1} \left( \frac{\partial w}{\partial \alpha} - u^+ \right) \\ \text{在 } \gamma = -h_2 \text{ 处: } & u^{\circ-} = u^- - \frac{t_2}{2R_1} \left( \frac{\partial w}{\partial \alpha} - u^- \right) \end{aligned} \right\} \quad (2.12a, b)$$

那么就可以求得夹心的位移:

$$\begin{aligned} u^{\circ} = & u^+ + \frac{t_1}{2R_1} \left( \frac{\partial w}{\partial \alpha} - u^+ \right) - \left( \frac{h_1}{h_1 + h_2} - \frac{\gamma}{h_1 + h_2} \right) \\ & \cdot \left[ \frac{(t_1 + t_2)}{2R_1} \frac{\partial w}{\partial \alpha} + (u^+ - u^-) - \frac{t_1 u^+ + t_2 u^-}{2R_1} \right] \end{aligned} \quad (2.13a)$$

同理:

$$\begin{aligned} v^{\circ} = & v^+ + \frac{t_2}{2R_2 \sin \alpha} \frac{\partial w}{\partial \beta} - \frac{t_2}{2R_2} v^+ - \left( \frac{h_1}{h_1 + h_2} - \frac{\gamma}{h_1 + h_2} \right) \\ & \cdot \left[ \frac{(t_1 + t_2)}{2R_2 \sin \alpha} \frac{\partial w}{\partial \beta} + (v^+ - v^-) - \frac{t_1 v^+ + t_2 v^-}{2R_2} \right] \end{aligned} \quad (2.13b)$$

由 (2.5)、(2.10)、(2.13) 式可得

$$\left. \begin{aligned} e_{13}^{\circ} = & \frac{k}{h_1 + h_2} \cdot \left( \psi_{\alpha} + \frac{1}{R_1} \frac{\partial w}{\partial \alpha} - \frac{u}{R_1} \right) \\ e_{23}^{\circ} = & \frac{k}{h_1 + h_2} \cdot \left( \psi_{\beta} + \frac{1}{R_2 \sin \alpha} \frac{\partial w}{\partial \beta} - \frac{v}{R_2} \right) \end{aligned} \right\} \quad (2.14a, b)$$

(2.14) 式代入 (2.9)、(2.8) 式得

$$\left. \begin{aligned} Q_1^{\circ} = & G^{\circ} \cdot k \cdot \left( \psi_{\alpha} + \frac{1}{R_1} \frac{\partial w}{\partial \alpha} - \frac{u}{R_1} \right) \\ Q_2^{\circ} = & G^{\circ} \cdot k \cdot \left( \psi_{\beta} + \frac{1}{R_2 \sin \alpha} \frac{\partial w}{\partial \beta} - \frac{v}{R_2} \right) \end{aligned} \right\} \quad (2.15a, b)$$

夹层旋转壳的广义变分表达式为

$$\delta V = \delta V^+ + \delta V^- + \delta V^{\circ} = 0 \quad (2.16)$$

其中

$$\begin{aligned} \delta V^{\pm} = & \int_{\alpha_1}^{\alpha_2} \int_{\beta_1}^{\beta_2} [N_1^{\pm} \delta e_1^{\pm} + N_2^{\pm} \delta e_2^{\pm} + S^{\pm} \delta e_3^{\pm} + M_1^{\pm} \delta \chi_1^{\pm} \\ & + M_2^{\pm} \delta \chi_2^{\pm} + 2M_{12}^{\pm} \delta \chi_{12}^{\pm} - p^{\pm} \delta w] R_1 R_2 \sin \alpha \, d\beta \, d\alpha \\ & - \int_{\alpha_1}^{\alpha_2} \left\{ \left[ \bar{N}_2^{\pm} \delta v^{\pm} + \bar{S}^{\pm} \delta u^{\pm} - \frac{\bar{M}_2^{\pm}}{R_2 \sin \alpha} \delta \left( \frac{\partial w}{\partial \beta} \right) \right. \right. \\ & \left. \left. + \bar{Q}_2^{\pm} \delta w \right] R_1 \right\}_{\beta_1}^{\beta_2} d\alpha - \int_{\beta_1}^{\beta_2} \left\{ \bar{N}_1^{\pm} \delta u^{\pm} + \bar{S}^{\pm} \delta v^{\pm} \right. \\ & \left. - \frac{\bar{M}_1^{\pm}}{R_1} \delta \left( \frac{\partial w}{\partial \alpha} \right) + \bar{Q}_1^{\pm} \delta w \right\} R_2 \sin \alpha \Big|_{\alpha_1}^{\alpha_2} d\beta \end{aligned} \quad (2.17)$$

$$\begin{aligned} \delta V^{\circ} = & \int_{\alpha_1}^{\alpha_2} \int_{\beta_1}^{\beta_2} (Q_1^{\circ} \delta e_{13}^{\circ} + Q_2^{\circ} \delta e_{23}^{\circ}) R_1 R_2 \sin \alpha \, d\beta \, d\alpha \\ & - \int_{\alpha_1}^{\alpha_2} \bar{Q}_2^{\circ} \delta w R_1 \Big|_{\beta_1}^{\beta_2} d\alpha - \int_{\beta_1}^{\beta_2} \bar{Q}_1^{\circ} \delta w R_2 \sin \alpha \Big|_{\alpha_1}^{\alpha_2} d\beta \end{aligned} \quad (2.18)$$

此处  $\bar{N}_i^\pm$ ,  $\bar{Q}_i^\pm$ ,  $\bar{M}_i^\pm$ , ( $i=1, 2$ ) 及  $\bar{S}^\pm$ ,  $\bar{Q}_1^\pm$ ,  $\bar{Q}_2^\pm$  等表示边界力。

将(2.4)、(2.14)、(2.5)、(2.6)式代入(2.17)、(2.18)式经过变分运算后再代入(2.16)式可得到

$$\begin{aligned}
 \delta V = & - \int_{\alpha_1}^{\alpha_2} \int_{\beta_1}^{\beta_2} \left\{ \left[ \frac{\partial}{\partial \alpha} (N_1 R_2 \sin \alpha) - N_2 R_1 \cos \alpha + R_1 \frac{\partial S}{\partial \beta} \right. \right. \\
 & + \frac{1}{R_1} \frac{\partial}{\partial \alpha} (M_1'' R_2 \sin \alpha) - M_2'' \cos \alpha + \frac{\partial M_{1,2}''}{\partial \beta} \\
 & + \frac{k}{h_1 + h_2} \cdot Q_1^c R_2 \sin \alpha \left. \right] \delta u + \left[ R_1 \frac{\partial N_2}{\partial \beta} + 2S R_1 \cos \alpha \right. \\
 & + \frac{\partial S}{\partial \alpha} \cdot R_2 \sin \alpha + \frac{R_1}{R_2} \cdot \frac{\partial M_2''}{\partial \beta} + \frac{1}{R_2^2 \sin \alpha} \cdot \frac{\partial}{\partial \alpha} (M_{1,2}'' R_2^2 \sin^2 \alpha) \\
 & + \frac{k}{h_1 + h_2} Q_2^c R_1 \sin \alpha \left. \right] \delta v + \left[ \frac{\partial}{\partial \alpha} (M_1' R_2 \sin \alpha) \right. \\
 & - M_2' R_1 \cos \alpha + R_1 \frac{\partial M_{1,2}'}{\partial \beta} - \frac{k}{h_1 + h_2} Q_1^c R_1 R_2 \sin \alpha \left. \right] \delta \psi_\alpha \\
 & + \left[ R_1 \frac{\partial M_2'}{\partial \beta} + 2M_{1,2}' R_1 \cos \alpha + \frac{\partial M_{1,2}'}{\partial \alpha} \cdot R_2 \sin \alpha \right. \\
 & - \frac{k}{h_1 + h_2} Q_2^c R_1 R_2 \sin \alpha \left. \right] \delta \psi_\beta \\
 & + \left[ \frac{\partial}{\partial \alpha} \left( \frac{1}{R_1} \frac{\partial}{\partial \alpha} (M_1'' R_2 \sin \alpha) \right) - N_1 R_2 \sin \alpha - N_2 R_1 \sin \alpha \right. \\
 & - \frac{\partial}{\partial \alpha} (M_2'' \cos \alpha) + \frac{R_1}{R_2 \sin \alpha} \frac{\partial^2 M_2''}{\partial \beta^2} + 2 \frac{\partial^2 M_{1,2}''}{\partial \alpha \partial \beta} \\
 & + \frac{2R_1 \operatorname{ctg} \alpha}{R_2} \cdot \frac{\partial M_{1,2}''}{\partial \beta} + \frac{k}{h_1 + h_2} \cdot \frac{\partial}{\partial \alpha} (Q_1^c R_2 \sin \alpha) \\
 & + \frac{k}{h_1 + h_2} \cdot R_1 \cdot \frac{\partial Q_2^c}{\partial \beta} + p \cdot R_1 R_2 \sin \alpha \left. \right] \delta w \left. \right\} d\beta d\alpha \\
 & - \int_{\alpha_1}^{\alpha_2} \left\{ \left[ (\bar{N}_2 - N_2) \delta v + (\bar{S} - S) \delta u - (\bar{M}_2'' - M_2'') \cdot \frac{1}{R_2 \sin \alpha} \delta \left( \frac{\partial w}{\partial \beta} \right) \right. \right. \\
 & + \left( \bar{Q}_2 - \frac{1}{R_2 \sin \alpha} \frac{\partial M_2''}{\partial \beta} - \frac{2 \operatorname{ctg} \alpha}{R_2} M_{1,2}'' - \frac{2}{R_1} \frac{\partial M_{1,2}''}{\partial \alpha} \right. \\
 & - \frac{k}{h_1 + h_2} Q_2^c \left. \right] \delta w + (\bar{M}_2' - M_2') \delta \psi_\beta + (\bar{M}_{1,2}' - M_{1,2}') \delta \psi_\alpha \left. \right] R_1 \left. \right\} d\alpha \\
 & - \int_{\beta_1}^{\beta_2} \left\{ \left[ (\bar{N}_1 - N_1) \delta u + (\bar{S} - S) \delta v - (\bar{M}_1'' - M_1'') \cdot \frac{1}{R_1} \delta \left( \frac{\partial w}{\partial \alpha} \right) \right. \right. \\
 & + (\bar{M}_1' - M_1') \delta \psi_\alpha + (\bar{M}_{1,2}' - M_{1,2}') \delta \psi_\beta \left. \right\}
 \end{aligned}$$

$$\begin{aligned}
& + \left( \bar{Q}_1 - \frac{1}{R_1 R_2 \sin \alpha} \cdot \frac{\partial}{\partial \alpha} (M_1'' R_2 \sin \alpha) + \frac{\operatorname{ctg} \alpha}{R_2} M_2'' \right. \\
& \left. - \frac{2}{R_2 \sin \alpha} \cdot \frac{\partial M_{1,2}''}{\partial \beta} - \frac{k}{h_1 + h_2} Q_1^c \right) \cdot \delta w \left. \right] R_2 \sin \alpha \Big\}_{\alpha_1}^{\alpha_2} d\beta \\
& - \left[ \left[ 2M_{1,2}'' \delta w \right]_{\alpha_1}^{\alpha_2} \right]_{\beta_1}^{\beta_2} = 0
\end{aligned} \tag{2.19}$$

此处

$$p = p^+ + p^-; \quad \bar{Q}_i = \bar{Q}_i^+ + \bar{Q}_i^- + \bar{Q}_i^0; \quad (i=1, 2)$$

由(2.19)式可得平衡微分方程:

$$\left. \begin{aligned}
& \frac{\partial}{\partial \alpha} (N_1 R_2 \sin \alpha) - N_2 R_1 \cos \alpha + R_1 \frac{\partial S}{\partial \beta} + \frac{1}{R_1} \cdot \frac{\partial}{\partial \alpha} (M_1'' R_2 \sin \alpha) \\
& - M_2'' \cos \alpha + \frac{\partial M_{1,2}''}{\partial \beta} + \frac{k}{h_1 + h_2} Q_1^c R_2 \sin \alpha = 0 \\
& R_1 \frac{\partial N_2}{\partial \beta} + 2S R_1 \cos \alpha + \frac{\partial S}{\partial \alpha} \cdot R_2 \sin \alpha + \frac{R_1}{R_2} \cdot \frac{\partial M_2''}{\partial \beta} \\
& + \frac{1}{R_2^2 \sin \alpha} \cdot \frac{\partial}{\partial \alpha} (M_{1,2}'' R_2^2 \sin^2 \alpha) + \frac{k}{h_1 + h_2} Q_2^c R_1 \sin \alpha = 0 \\
& \frac{\partial}{\partial \alpha} (M_1' R_2 \sin \alpha) - M_1' R_1 \cos \alpha + R_1 \frac{\partial M_{1,2}'}{\partial \beta} - \frac{k}{h_1 + h_2} Q_1^c R_1 R_2 \sin \alpha = 0 \\
& R_1 \frac{\partial M_2'}{\partial \beta} + 2M_{1,2}' R_1 \cos \alpha + \frac{\partial M_{1,2}'}{\partial \alpha} R_2 \sin \alpha - \frac{k}{h_1 + h_2} Q_2^c R_1 R_2 \sin \alpha = 0 \\
& \frac{\partial}{\partial \alpha} \left[ \frac{1}{R_1} \cdot \frac{\partial}{\partial \alpha} (M_1'' R_2 \sin \alpha) \right] - N_1 R_2 \sin \alpha - N_2 R_1 \sin \alpha \\
& - \frac{\partial}{\partial \alpha} (M_2'' \cos \alpha) + \frac{R_1}{R_2 \sin \alpha} \frac{\partial^2 M_2''}{\partial \beta^2} + 2 \frac{\partial^2 M_{1,2}''}{\partial \alpha \partial \beta} \\
& + \frac{2R_1 \operatorname{ctg} \alpha}{R_2} \cdot \frac{\partial M_{1,2}''}{\partial \beta} + \frac{k}{h_1 + h_2} \left[ \frac{\partial}{\partial \alpha} (Q_1^c R_2 \sin \alpha) \right. \\
& \left. + R_1 \frac{\partial Q_2^c}{\partial \beta} \right] + p R_1 R_2 \sin \alpha = 0
\end{aligned} \right\} \tag{2.20a~e}$$

边界条件为

在  $\alpha = \alpha_1, \alpha = \alpha_2$  上:

$$N_1 = \bar{N}_1 \quad \text{或} \quad \delta u = 0$$

$$S = \bar{S} \quad \text{或} \quad \delta v = 0$$

$$M_1'' = \bar{M}_1'' \quad \text{或} \quad \delta \left( \frac{\partial w}{\partial \alpha} \right) = 0$$

$$M_1' = \bar{M}_1' \quad \text{或} \quad \delta \psi_\alpha = 0$$

$$M_{1,2}'' = \bar{M}_{1,2}'' \quad \text{或} \quad \delta \psi_\beta = 0$$

$$\frac{1}{R_1 R_2 \sin \alpha} \frac{\partial}{\partial \alpha} (M_1'' R_2 \sin \alpha) - \frac{\operatorname{ctg} \alpha}{R_2} M_2'' + \frac{2}{R_2 \sin \alpha} \frac{\partial M_{1,2}''}{\partial \beta}$$

$$+ \frac{k}{h_1 + h_2} Q_1^c = \bar{Q}_1 \quad \text{或} \quad \delta w = 0$$

(2.21a~f)

在  $\beta = \beta_1, \beta = \beta_2$  上:

$$N_2 = \bar{N}_2 \quad \text{或} \quad \delta v = 0$$

$$S = \bar{S} \quad \text{或} \quad \delta u = 0$$

$$M_2'' = \bar{M}_2'' \quad \text{或} \quad \delta \left( \frac{\partial w}{\partial \beta} \right) = 0$$

$$M_2' = \bar{M}_2' \quad \text{或} \quad \delta \psi_\beta = 0$$

$$M_{1,2}' = \bar{M}_{1,2}' \quad \text{或} \quad \delta \psi_\alpha = 0$$

$$\frac{1}{R_2 \sin \alpha} \frac{\partial M_2''}{\partial \beta} + \frac{2 \operatorname{ctg} \alpha}{R_2} M_{1,2}'' + \frac{2}{R_1} \frac{\partial M_{1,2}''}{\partial \alpha} + \frac{k}{h_1 + h_2} Q_i^c = \bar{Q}_2$$

$$\text{或} \quad \delta w = 0$$

(2.22a~f)

由内外表层壳本身的微元平衡知:

$$\frac{\partial}{\partial \alpha} (\sigma_1^+ R_2 \sin \alpha) + R_1 \frac{\partial \tau_{1,2}^+}{\partial \beta} + R_1 R_2 \sin \alpha \cdot \frac{\partial \tau_{1,2}^+}{\partial \gamma} - R_1 \cos \alpha \cdot \sigma_2^+ = 0$$

$$R_1 \frac{\partial \sigma_2^+}{\partial \beta} + \frac{\partial}{\partial \alpha} (\tau_{1,2}^+ R_2 \sin \alpha) + R_1 R_2 \sin \alpha \cdot \frac{\partial \tau_{2,3}^+}{\partial \gamma} + R_1 \cos \alpha \cdot \tau_{1,2}^+ = 0$$

(2.23a, b)

若注意到

$$\text{在 } \gamma = h_1 + t_1 \text{ 处:} \quad \tau_{1,3}^+ = \tau_{2,3}^+ = 0$$

$$\text{在 } \gamma = -(h_2 + t_2) \text{ 处:} \quad \tau_{1,3}^- = \tau_{2,3}^- = 0$$

(2.24a, b)

而且由 (2.6) 式可知

$$N_i^+ = \frac{B_1}{B_1 + B_2} N_i + \frac{1}{k} \cdot M_i' \quad (i = 1, 2)$$

$$M_i^+ = \frac{M_i''}{2} + M_i'$$

$$S^+ = \frac{B_1}{B_1 + B_2} \cdot S + \frac{1}{k} \cdot M_{1,2}'$$

$$M_{1,2}^+ = \frac{M_{1,2}''}{2} + M_{1,2}'$$

(2.25a, b, c, d)

从而

$$\sigma_1^+ = \frac{1}{(B_1 + B_2)t_1} \left( B_1 N_1 + \frac{B_1 + B_2}{k} M_1' \right)$$

$$+ \frac{12}{t_1^3} \left( -\frac{M_1''}{2} + M_1' \right) \cdot \left( \gamma - h_1 - \frac{t_1}{2} \right)$$

$$\sigma_2^+ = \frac{1}{(B_1 + B_2)t_1} \left( B_1 N_2 + \frac{B_1 + B_2}{k} M_2' \right)$$

$$+ \frac{12}{t_1^3} \left( -\frac{M_2''}{2} + M_2' \right) \left( \gamma - h_1 - \frac{t_1}{2} \right)$$

$$\tau_{1,2}^+ = \frac{1}{(B_1 + B_2)t_1} \left( B_1 S + \frac{B_1 + B_2}{k} M_{1,2}' \right)$$

$$+ \frac{12}{t_1^3} \left( -\frac{M_{1,2}''}{2} + M_{1,2}' \right) \left( \gamma - h_1 - \frac{t_1}{2} \right)$$

(2.26a, b, c)



于是由 (2.23)、(2.24)、(2.26) 式可求得  $Q_i^+$  如下:

$$\begin{aligned} & \int_{h_1}^{h_1+t_1} \left[ \frac{\partial}{\partial \alpha} (\sigma_1^+ R_2 \sin \alpha) + R_1 \frac{\partial \tau_{12}^+}{\partial \beta} \right] \left( \gamma - h_1 - \frac{t_1}{2} \right) d\gamma \\ &= \frac{\partial}{\partial \alpha} \left[ \left( -\frac{M_1''}{2} + M_1^t \right) R_2 \sin \alpha \right] + R_1 \frac{\partial}{\partial \beta} \left( -\frac{M_{12}''}{2} + M_{12}^t \right) \\ &= \int_{h_1}^{h_1+t_1} \left( \sigma_1^+ R_1 \cos \alpha - \frac{\partial \tau_{13}^+}{\partial \gamma} R_1 R_2 \sin \alpha \right) \left( \gamma - h_1 - \frac{t_1}{2} \right) d\gamma \\ &= R_1 \cos \alpha \left( -\frac{M_2''}{2} + M_2^t \right) + R_1 R_2 \sin \alpha \cdot \left[ \left( h_1 + \frac{t_1}{2} \right) \tau_{13}^+ \Big|_{h_1}^{h_1+t_1} \right. \\ & \quad \left. - \gamma \tau_{13}^+ \Big|_{h_1}^{h_1+t_1} + \int_{h_1}^{h_1+t_1} \tau_{13}^+ d\gamma \right] \\ &= R_1 \cos \alpha \left( -\frac{M_2''}{2} + M_2^t \right) + R_1 R_2 \sin \alpha \cdot \left( -\frac{t_1}{2} \frac{Q_i^c}{h_1+h_2} + Q_i^+ \right) \end{aligned}$$

因此

$$\begin{aligned} Q_i^+ &= \frac{1}{R_1 R_2 \sin \alpha} \left\{ \frac{\partial}{\partial \alpha} \left[ \left( -\frac{M_1''}{2} + M_1^t \right) R_2 \sin \alpha \right] \right. \\ & \quad \left. + R_1 \frac{\partial}{\partial \beta} \left( -\frac{M_{12}''}{2} + M_{12}^t \right) - R_1 \cos \alpha \left( -\frac{M_2''}{2} + M_2^t \right) \right\} + \frac{t_1}{2} \cdot \frac{Q_i^c}{(h_1+h_2)} \end{aligned}$$

同理

$$\begin{aligned} Q_i^- &= \frac{1}{R_1 R_2 \sin \alpha} \left\{ \frac{\partial}{\partial \alpha} \left[ \left( \frac{M_1''}{2} - M_1^t \right) R_2 \sin \alpha \right] + R_1 \frac{\partial}{\partial \beta} \left( \frac{M_{12}''}{2} - M_{12}^t \right) \right. \\ & \quad \left. - R_1 \cos \alpha \left( \frac{M_2''}{2} - M_2^t \right) \right\} + \frac{t_2}{2} \cdot \frac{Q_i^c}{(h_1+h_2)} \end{aligned}$$

从而

$$\left. \begin{aligned} Q_i^+ + Q_i^- &= \frac{1}{R_1 R_2 \sin \alpha} \left[ \frac{\partial}{\partial \alpha} (M_1'' R_2 \sin \alpha) + R_1 \frac{\partial M_{12}''}{\partial \beta} \right. \\ & \quad \left. - R_1 \cos \alpha \cdot M_2'' \right] + \frac{(t_1+t_2)}{2} \cdot \frac{Q_i^c}{(h_1+h_2)} \\ Q_i^+ - Q_i^- &= \frac{1}{R_1 R_2 \sin \alpha} \left[ R_1 \frac{\partial M_{12}''}{\partial \beta} + R_1 \cos \alpha \cdot M_{12}^t \right. \\ & \quad \left. + \frac{\partial}{\partial \alpha} (M_{12}'' R_2 \sin \alpha) \right] + \frac{(t_1+t_2)}{2} \cdot \frac{Q_i^c}{(h_1+h_2)} \end{aligned} \right\} \quad (2.27a, b)$$

同理

若令

$$\left. \begin{aligned} M_i &= M_i^+ + M_i^- \\ M_{i2} &= M_{i2}^+ + M_{i2}^- \quad (i=1, 2) \\ Q_i &= Q_i^+ + Q_i^- + Q_i^c \end{aligned} \right\} \quad (2.28a, b, c)$$

将 (2.27)、(2.28) 式代入 (2.20) 式即可得到:

$$\left. \begin{aligned}
 & \frac{\partial}{\partial \alpha} (N_1 R_2 \sin \alpha) - N_2 R_1 \cos \alpha + R_1 \frac{\partial S}{\partial \beta} + Q_1 R_2 \sin \alpha = 0 \\
 & \frac{\partial S}{\partial \alpha} R_2 \sin \alpha + 2S \cdot R_1 \cos \alpha + R_1 \frac{\partial N_2}{\partial \beta} + Q_2 R_1 \sin \alpha = 0 \\
 & \frac{\partial}{\partial \alpha} (M_1 R_2 \sin \alpha) - M_2 R_1 \cos \alpha + R_1 \frac{\partial M_{12}}{\partial \beta} - Q_1 R_1 R_2 \sin \alpha = 0 \\
 & \frac{\partial M_{12}}{\partial \alpha} R_2 \sin \alpha + 2M_{12} R_1 \cos \alpha + R_1 \frac{\partial M_2}{\partial \beta} - Q_2 R_1 R_2 \sin \alpha = 0 \\
 & \frac{\partial}{\partial \alpha} (Q_1 R_2 \sin \alpha) + R_1 \frac{\partial Q_2}{\partial \beta} - N_1 R_2 \sin \alpha - N_2 R_1 \sin \alpha + p R_1 R_2 \sin \alpha = 0
 \end{aligned} \right\} (2.29a \sim e)$$

可见夹层旋转壳与单层旋转壳的平衡方程形式完全相同。

今令

$$\begin{aligned}
 M_1 &= \int_{h_1}^{h_1+t_1} \sigma_1^+ \gamma d\gamma + \int_{-(h_2+t_2)}^{-h_2} \sigma_1^- \gamma d\gamma \\
 &= \left( h_1 + \frac{t_1}{2} \right) N_1^+ - \left( h_2 + \frac{t_2}{2} \right) N_1^- + M_1^+ + M_1^-
 \end{aligned}$$

将 (2.6)、(2.28) 式代入上式则有

$$B_1 \left( h_1 + \frac{t_1}{2} \right) = B_2 \left( h_2 + \frac{t_2}{2} \right) \quad (2.30)$$

(2.30) 式确定了  $\alpha\beta$  坐标面的位置。

## 2. 广义力-广义位移关系

由 (2.6)、(2.2)、(2.4)、(2.5) 式可得

$$\begin{aligned}
 N_1 &= B_1 \cdot (e_1^+ + \mu e_2^+) + B_2 (e_1^- + \mu e_2^-) \\
 &= (B_1 + B_2) \cdot \left[ \frac{1}{R_1} \cdot \left( \frac{\partial u}{\partial \alpha} + w \right) \right. \\
 &\quad \left. + \frac{\mu}{R_2} \left( \frac{1}{\sin \alpha} \cdot \frac{\partial v}{\partial \beta} + \operatorname{ctg} \alpha \cdot u + w \right) \right]
 \end{aligned}$$

同理:

$$\begin{aligned}
 N_2 &= (B_1 + B_2) \cdot \left[ \frac{1}{R_2} \left( \frac{1}{\sin \alpha} \cdot \frac{\partial v}{\partial \beta} + \operatorname{ctg} \alpha \cdot u + w \right) + \frac{\mu}{R_1} \left( \frac{\partial u}{\partial \alpha} + w \right) \right] \\
 S &= \frac{1}{2} (1 - \mu) (B_1 + B_2) \left[ \frac{1}{R_2 \sin \alpha} \cdot \frac{\partial u}{\partial \beta} + \frac{R_2 \sin \alpha}{R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{v}{R_2 \sin \alpha} \right) \right] \\
 M_1^+ &= \frac{B_1 B_2 k^2}{B_1 + B_2} \left[ \frac{1}{R_1} \cdot \frac{\partial \psi_\alpha}{\partial \alpha} + \frac{\mu}{R_2} \left( \frac{1}{\sin \alpha} \cdot \frac{\partial \psi_\beta}{\partial \beta} + \operatorname{ctg} \alpha \cdot \psi_\alpha \right) \right] \\
 M_1^- &= \frac{B_1 B_2 k^2}{B_1 + B_2} \left[ \frac{1}{R_2} \left( \frac{1}{\sin \alpha} \cdot \frac{\partial \psi_\beta}{\partial \beta} + \operatorname{ctg} \alpha \cdot \psi_\alpha \right) + \frac{\mu}{R_1} \cdot \frac{\partial \psi_\alpha}{\partial \alpha} \right] \\
 M_{12} &= \frac{1}{2} (1 - \mu) \cdot \frac{B_1 B_2 k^2}{B_1 + B_2} \left[ \frac{1}{R_2 \sin \alpha} \cdot \frac{\partial \psi_\alpha}{\partial \beta} + \frac{R_2 \sin \alpha}{R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{\psi_\beta}{R_2 \sin \alpha} \right) \right]
 \end{aligned}$$

$$\begin{aligned}
 M_1'' &= -(D_1 + D_2) \cdot \left[ \frac{1}{R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{1}{R_1} \cdot \frac{\partial w}{\partial \alpha} - \frac{u}{R_1} \right) + \mu \left( \frac{1}{R_2^2 \sin^2 \alpha} \cdot \frac{\partial^2 w}{\partial \beta^2} \right. \right. \\
 &\quad \left. \left. + \frac{\operatorname{ctg} \alpha}{R_1 R_2} \cdot \frac{\partial w}{\partial \alpha} - \frac{\operatorname{ctg} \alpha}{R_1 R_2} \cdot u - \frac{1}{R_2^2 \sin \alpha} \cdot \frac{\partial v}{\partial \beta} \right) \right] \\
 M_2'' &= -(D_1 + D_2) \cdot \left[ \frac{1}{R_2^2 \sin^2 \alpha} \cdot \frac{\partial^2 w}{\partial \beta^2} + \frac{\operatorname{ctg} \alpha}{R_1 R_2} \left( \frac{\partial w}{\partial \alpha} - u \right) \right. \\
 &\quad \left. - \frac{1}{R_2^2 \sin \alpha} \cdot \frac{\partial v}{\partial \beta} + \frac{\mu}{R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{1}{R_1} \cdot \frac{\partial w}{\partial \alpha} - \frac{u}{R_1} \right) \right] \\
 M_{12}'' &= -(1 - \mu)(D_1 + D_2) \left[ \frac{1}{R_1 R_2 \sin \alpha} \cdot \left( \frac{\partial^2 w}{\partial \alpha \partial \beta} - \frac{R_1 \operatorname{ctg} \alpha}{R_2} \cdot \frac{\partial w}{\partial \beta} \right) \right. \\
 &\quad \left. - \frac{1}{2 R_1 R_2 \sin \alpha} \cdot \frac{\partial u}{\partial \beta} - \frac{R_2 \sin \alpha}{2 R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{v}{R_2^2 \sin \alpha} \right) \right] \\
 M_1' &= -\frac{1}{2} \cdot (D_1 - D_2) \cdot \left[ \frac{1}{R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{1}{R_1} \cdot \frac{\partial w}{\partial \alpha} - \frac{u}{R_1} \right) + \mu \left( \frac{1}{R_2^2 \sin^2 \alpha} \right. \right. \\
 &\quad \left. \left. \cdot \frac{\partial^2 w}{\partial \beta^2} + \frac{\operatorname{ctg} \alpha}{R_1 R_2} \cdot \frac{\partial w}{\partial \alpha} - \frac{\operatorname{ctg} \alpha}{R_1 R_2} \cdot u - \frac{1}{R_2^2 \sin \alpha} \cdot \frac{\partial v}{\partial \beta} \right) \right] \\
 M_2' &= -\frac{1}{2} (D_1 - D_2) \cdot \left[ \frac{1}{R_2^2 \sin^2 \alpha} \cdot \frac{\partial^2 w}{\partial \beta^2} + \frac{\operatorname{ctg} \alpha}{R_1 R_2} \left( \frac{\partial w}{\partial \alpha} - u \right) \right. \\
 &\quad \left. - \frac{1}{R_2^2 \sin \alpha} \cdot \frac{\partial v}{\partial \beta} + \frac{\mu}{R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{1}{R_1} \cdot \frac{\partial w}{\partial \alpha} - \frac{u}{R_1} \right) \right] \\
 M_{12}' &= -\frac{1}{2} (1 - \mu)(D_1 - D_2) \cdot \left[ \frac{1}{R_1 R_2 \sin \alpha} \left( \frac{\partial^2 w}{\partial \alpha \partial \beta} - \frac{R_1 \operatorname{ctg} \alpha}{R_2} \cdot \frac{\partial w}{\partial \beta} \right) \right. \\
 &\quad \left. - \frac{1}{2 R_1 R_2 \sin \alpha} \cdot \frac{\partial u}{\partial \beta} - \frac{R_2 \sin \alpha}{2 R_1} \cdot \frac{\partial}{\partial \alpha} \left( \frac{v}{R_2^2 \sin \alpha} \right) \right] \\
 Q_1' &= G^0 \cdot k \cdot \left( \psi_\alpha + \frac{1}{R_1} \cdot \frac{\partial w}{\partial \alpha} - \frac{u}{R_1} \right) \\
 Q_2' &= G^0 \cdot k \cdot \left( \psi_\beta + \frac{1}{R_2 \sin \alpha} \cdot \frac{\partial w}{\partial \beta} - \frac{v}{R_2} \right)
 \end{aligned} \tag{2.31a~n}$$

### 三、几个特例

#### 1. 具有不等厚表板的夹层板

如果令  $R_1 = \infty$ ,  $R_2 = \infty$ , 并采用直角坐标系, 则(2.29)式将化为:

$$\left. \begin{aligned}
 \frac{\partial M_x}{\partial x} + \frac{\partial M_{xy}}{\partial y} - Q_x &= 0 \\
 \frac{\partial M_y}{\partial y} + \frac{\partial M_{xy}}{\partial x} - Q_y &= 0 \\
 \frac{\partial Q_x}{\partial x} + \frac{\partial Q_y}{\partial y} + p &= 0
 \end{aligned} \right\} \tag{3.1a,b,c}$$

而(2.31)式化为:

$$\left. \begin{aligned} M_x &= \frac{B_1 B_2 k^2}{B_1 + B_2} \cdot \left( \frac{\partial \psi_x}{\partial x} + \mu \frac{\partial \psi_y}{\partial y} \right) - (D_1 + D_2) \left( \frac{\partial^2 w}{\partial x^2} + \mu \frac{\partial^2 w}{\partial y^2} \right) \\ M_y &= \frac{B_1 B_2 k^2}{B_1 + B_2} \cdot \left( \frac{\partial \psi_y}{\partial y} + \mu \frac{\partial \psi_x}{\partial x} \right) - (D_1 + D_2) \left( \frac{\partial^2 w}{\partial y^2} + \mu \frac{\partial^2 w}{\partial x^2} \right) \\ M_{xy} &= \frac{1}{2} (1 - \mu) \cdot \left[ \frac{B_1 B_2 k^2}{B_1 + B_2} \left( \frac{\partial \psi_x}{\partial y} + \frac{\partial \psi_y}{\partial x} \right) - 2(D_1 + D_2) \cdot \frac{\partial^2 w}{\partial x \partial y} \right] \\ Q_x &= -(D_1 + D_2) \cdot \frac{\partial}{\partial x} \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} \right) + \frac{G^o \cdot k^2}{h_1 + h_2} \cdot \left( \psi_x + \frac{\partial w}{\partial x} \right) \\ Q_y &= -(D_1 + D_2) \cdot \frac{\partial}{\partial y} \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} \right) + \frac{G^o \cdot k^2}{h_1 + h_2} \cdot \left( \psi_y + \frac{\partial w}{\partial y} \right) \end{aligned} \right\} \quad (3.2a \sim e)$$

若注意到当内外表板为同一材料制成时有

$$\frac{B_1 B_2 k^2}{B_1 + B_2} = \frac{E}{1 - \mu^2} \cdot \left[ t_1 \left( h_1 + \frac{t_1}{2} \right)^2 + t_2 \left( h_2 + \frac{t_2}{2} \right)^2 \right]$$

则由本文就可得到与文献[4]完全相同的结果。

## 2. 对称加载的夹层圆锥壳

取坐标系如图3所示, 此时有  $R_1 = \infty$ ,  $R_2 = s \cdot \operatorname{tg} \alpha$  则(2.29)式成为:

$$\left. \begin{aligned} \frac{d}{ds} (N_s \cdot s) - N_\theta &= 0 \\ \frac{d}{ds} (M_s \cdot s) - M_\theta - Q_s \cdot s &= 0 \\ \frac{d}{ds} (Q_s \cdot s) - N_\theta \cdot \operatorname{ctg} \alpha + p \cdot s &= 0 \end{aligned} \right\}$$

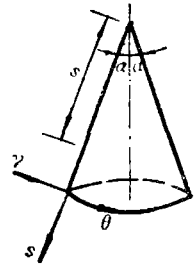


图 3  
(3.3a, b, c)

当内外表层壳厚度相同且由同一材料制成时,  $t_1 = t_2 = t$ ,  $E_1 = E_2 = E$ ; 则(2.31)式化为:

$$\left. \begin{aligned} N_s &= \frac{2Et}{(1-\mu^2)} \cdot \left[ \frac{du}{ds} + \frac{\mu}{s} (u - w \cdot \operatorname{ctg} \alpha) \right] \\ N_\theta &= \frac{2Et}{(1-\mu^2)} \left[ \frac{1}{s} \cdot (u - w \operatorname{ctg} \alpha) + \mu \cdot \frac{du}{ds} \right] \\ M_s' &= \frac{Et k^2}{2(1-\mu^2)} \left[ \frac{d\psi_s}{ds} + \frac{\mu}{s} \cdot \psi_s \right] \\ M_\theta' &= \frac{Et k^2}{2(1-\mu^2)} \cdot \left[ \frac{\psi_s}{s} + \mu \frac{d\psi_s}{ds} \right] \\ M_s'' &= -\frac{Et^3}{6(1-\mu^2)} \cdot \left( \frac{d^2 w}{ds^2} + \frac{\mu}{s} \frac{dw}{ds} \right) \\ M_\theta'' &= -\frac{Et^3}{6(1-\mu^2)} \cdot \left( \frac{1}{s} \cdot \frac{dw}{ds} + \mu \frac{d^2 w}{ds^2} \right) \\ Q_s' &= G^o \cdot k \cdot \left( \psi_s + \frac{dw}{ds} \right) \end{aligned} \right\} \quad (3.4a \sim g)$$

从而得到与文献[3]一致的结果。

### 3. 对称加载时夹层旋转壳的弯曲问题

当对称加载时广义内力  $S = M'_{12} = M''_{12} = Q_2 = 0$ , 广义位移  $v = 0$ . 且其余的广义力, 广义位移都仅是  $\alpha$  的函数. 此时由(2.29)及(2.20c)式可得平衡方程为:

$$\left. \begin{aligned} \frac{1}{R_1} \cdot \frac{d}{d\alpha} (N_1 R_2 \sin \alpha) - N_2 \cos \alpha + \frac{R_2 \sin \alpha}{R_1} \cdot Q_1 &= 0 \\ \frac{N_1}{R_1} + \frac{N_2}{R_2} - \frac{1}{R_1 R_2 \sin \alpha} \cdot \frac{d}{d\alpha} (Q_1 R_2 \sin \alpha) + p &= 0 \\ \frac{1}{R_1} \cdot \frac{d}{d\alpha} (M_1 R_2 \sin \alpha) - M_2 \cos \alpha - Q_1 R_2 \sin \alpha &= 0 \\ \frac{1}{R_1} \cdot \frac{d}{d\alpha} (M'_1 R_2 \sin \alpha) - M'_2 \cos \alpha - \frac{k}{h_1 + h_2} \cdot Q'_1 R_2 \sin \alpha &= 0 \end{aligned} \right\} \quad (3.5a, b, c, d)$$

1) 薄膜解: (下标加“0”)

此时(3.5)式成为:

$$\left. \begin{aligned} \frac{1}{R_1} \cdot \frac{d}{d\alpha} (N_{10} R_2 \sin \alpha) - N_{20} \cos \alpha &= 0 \\ \frac{N_{10}}{R_1} + \frac{N_{20}}{R_2} + p &= 0 \end{aligned} \right\} \quad (3.6a, b)$$

由(3.6b)知

$$N_{20} = -R_2 p - \frac{R_2}{R_1} N_{10} \quad (3.7)$$

(3.7)代入(3.6a)式得:

$$\frac{1}{R_1} \cdot \frac{dN_{10}}{d\alpha} + \left( \frac{1}{R_1} + \frac{1}{R_2} \right) \text{ctg} \alpha \cdot N_{10} = -p \cdot \text{ctg} \alpha \quad (3.8)$$

若引入应力函数  $U(\alpha)$  使得:

$$N_{10} = U(\alpha) / R_2 \sin^2 \alpha \quad (3.9)$$

(3.9)代入(3.8)式:

$$\frac{dU}{d\alpha} = -p \cdot R_1 R_2 \sin \alpha \cos \alpha$$

因此可解得

$$U(\alpha) = - \int_{\alpha} p R_1 R_2 \sin \alpha \cos \alpha d\alpha + C_1$$

$$N_{10} = - \frac{1}{R_2 \sin^2 \alpha} \cdot \int_{\alpha} p R_1 R_2 \sin \alpha \cos \alpha d\alpha + C_1$$

其中  $C_1$  为常数, 可由边界条件确定

2) 边界效应解:

令外载荷  $p=0$ , 引入应力函数  $F(\alpha)$  使得:

$$\left. \begin{aligned} N_2 &= \frac{1}{R_1} \cdot \frac{dF}{d\alpha} \\ N_1 R_2 \sin \alpha &= F \cos \alpha \\ Q_1 R_2 &= F \end{aligned} \right\} \quad (3.10a, b, c)$$

此时

将(3.10)式代入(3.5a, b)式可见满足此二平衡方程。

在对称加载时, 广义内力-广义应变-广义位移关系可由(2.31)式求得为:

$$\left. \begin{aligned} N_1 &= (B_1 + B_2) (\varepsilon_1 + \mu \varepsilon_2) \\ N_2 &= (B_1 + B_2) (\varepsilon_2 + \mu \varepsilon_1) \\ M_1' &= D \cdot \left( \frac{1}{R_1} \cdot \frac{d\psi_a}{d\alpha} + \mu \cdot \frac{\text{ctg} \alpha}{R_2} \cdot \psi_a \right) \\ M_2' &= D \left( \frac{\text{ctg} \alpha}{R_2} \psi_a + \frac{\mu}{R_1} \cdot \frac{d\psi_a}{d\alpha} \right) \\ M_1'' &= -D_f (\chi_1 + \mu \chi_2) \\ M_2'' &= -D_f (\chi_2 + \mu \chi_1) \\ Q_1' &= G^0 \cdot k \cdot \left( \psi_a + \frac{1}{R_1} \cdot \frac{dw}{d\alpha} - \frac{u}{R_1} \right) \end{aligned} \right\} \quad (3.11a \sim g)$$

其中

$$\left. \begin{aligned} D &= \frac{B_1 B_2 k^2}{B_1 + B_2} \\ D_f &= D_1 + D_2 \\ \varepsilon_1 &= \frac{1}{R_1} \cdot \frac{du}{d\alpha} + \frac{w}{R_1} \\ \varepsilon_2 &= \frac{\text{ctg} \alpha}{R_2} u + \frac{w}{R_2} \\ \chi_1 &= \frac{1}{R_1} \cdot \frac{d}{d\alpha} \left( \frac{1}{R_1} \cdot \frac{dw}{d\alpha} - \frac{u}{R_1} \right) \\ \chi_2 &= \frac{\text{ctg} \alpha}{R_2} \left( \frac{1}{R_1} \cdot \frac{dw}{d\alpha} - \frac{u}{R_1} \right) \end{aligned} \right\} \quad (3.12a \sim f)$$

若引入位移函数  $\varphi(\alpha) = \frac{1}{R_1} \cdot \frac{dw}{d\alpha} - \frac{u}{R_1}$ , 则可得到变形协调方程为:

$$\frac{1}{R_1} \frac{d}{d\alpha} (\varepsilon_2 R_2 \sin \alpha) - \varepsilon_1 \cos \alpha - \varphi \cdot \sin \alpha = 0 \quad (3.13)$$

由(3.10)、(3.11)式得

$$\left. \begin{aligned} \varepsilon_1 &= \frac{1}{B} (N_1 - \mu N_2) = \frac{1}{B} \cdot \left( \frac{\text{ctg} \alpha}{R_2} \cdot F - \frac{\mu}{R_1} \cdot \frac{dF}{d\alpha} \right) \\ \varepsilon_2 &= \frac{1}{B} (N_2 - \mu N_1) = \frac{1}{B} \cdot \left( \frac{1}{R_1} \cdot \frac{dF}{d\alpha} - \mu \cdot \frac{\text{ctg} \alpha}{R_2} \cdot F \right) \end{aligned} \right\} \quad (3.14a, b)$$

此处  $B = (B_1 + B_2) (1 - \mu^2)$

(3.14)式代入(3.13)式可得协调方程

$$L(F) + \frac{\mu}{R_1 R_2} \cdot F = B \cdot \frac{\varphi}{R_2} \quad (3.15)$$

此处微分算子  $L(\ )$  为:

$$L(\ ) = \frac{1}{R_1} \cdot \frac{d}{d\alpha} \left[ \frac{1}{R_1} \cdot \frac{d(\ )}{d\alpha} \right] + \frac{\text{ctg } \alpha}{R_1 R_2} \cdot \frac{d(\ )}{d\alpha} - \frac{\text{ctg}^2 \alpha}{R_1^2} (\ )$$

将(3.11c, d)、(3.11g)式代入(3.5d)式得:

$$L(\psi_\alpha) - \frac{\mu}{R_1 R_2} \psi_\alpha - \frac{C}{D} (\psi_\alpha + \varphi) = 0 \quad (3.16)$$

此处

$$C = \frac{G^0 \cdot h^2}{h_1 + h_2} \text{ 为剪切刚度.}$$

将(3.11c)~(3.11f)代入(3.5c)式得

$$D \left[ L(\psi_\alpha) - \frac{\mu}{R_1 R_2} \psi_\alpha \right] - D_f \left[ L(\varphi) - \frac{\mu}{R_1 R_2} \varphi \right] = \frac{F}{R_2} \quad (3.17)$$

最后将(3.16)、(3.17)式代入(3.15)式即可得到一个只含  $\psi_\alpha$  的六阶微分方程:

$$C \cdot [L(R_2 L)] \psi_\alpha - D_f [L(R_2 L^2) - \frac{C}{D} \cdot L(R_2 L)] \psi_\alpha - \frac{B}{R_2} \left( L - \frac{C}{D} \right) \psi_\alpha = 0 \quad (3.18)$$

由此可结合相应的边界条件求解。将薄膜解与边界效应解迭加即为完全解。

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## On the Problems of Sandwich Shells Having the Form of a Surface of Revolution and Face Layers of Non-Equal Thicknesses

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### Abstract

Fundamental equations which govern the behavior of an elastic sandwich shell having the form of a surface of revolution and face layers of non-equal thicknesses are derived, with the solution of refs. [3] and [4] as special examples.

The problems of the shell under the action of symmetrical loads are reduced to the solution of a displacement-function  $\psi_\alpha$ , where  $\psi_\alpha$  satisfies a differential equation of sixth order.